

# Save energy and maximize performance with versatile inverter

- Triple rating: Normal Duty (ND), Low Duty (LD), and Very Low Duty (VLD)
- PM motor control helps save energy
- Safety function IEC 61800-5-2 "Safe Torque Off (STO)"
   Conforms to machinery directive with ISO13849-1 (Category 4/PLe)
- DriveProgramming allows simple sequence control without a PLC
- EtherCAT communication using an optional communication unit provides high-speed communication for running and stopping, monitoring operating status, and changing various settings



## **Performance Specifications**

#### **Inverter 3G3RX2**

3-phase 200-V Class

Very Low Duty (VLD)/Low Duty (LD)/Normal Duty (ND)

30	3RX2-A2		]	A2004	A2007	A2015	A2022	A2037	A2055	A2075	A2110	A2150	A2185	A2220	A2300	A2370	A2450	A2550
			VLD	0.75	1.5	2.2	3.7	5.5	7.5	11	15	18.5	22	30	37	45	55	75
	ble motor capacity (l	λWΛ	LD	0.75	1.5	2.2	3.7	5.5	7.5	11	15	18.5	22	30	37	45	55	75
(4 poic)	capacity (i	,	ND	0.4	0.75	1.5	2.2	3.7	5.5	7.5	11	15	18.5	22	30	37	45	55
			VLD	4.4	8.0	10.4	15.6	22.8	33.0	46.0	60.0	80.0	93.0	124	153	185	229	295
	Rated out		LD	3.7	6.3	9.4	12.0	19.6	30.0	40.0	56.0	73.0	85.0	113	140	169	210	270
	ourrent (F	ν,	ND	3.2	5.0	8.0	11.0	17.5	25.0	32.0	46.0	64.0	76.0	95.0	122	146	182	220
			VLD	D 110% 60 sec / 120% 3 sec														
	Overload LD		120% 60 sec / 150% 3 sec															
	Current	unig	ND	150% 6	0 sec / 2	00% 3 se	ec											
Output	Rated out	tput vol	ltage	3-phase	e (3-wire)	200 to 2	40 V (de	pending	on receiv	ing volta	ge)							
			VLD	1.5	2.8	3.6	5.4	7.9	11.4	15.9	20.8	27.7	32.2	43.0	53.0	64.1	79.3	102.2
		200 V	LD	1.3	2.2	3.3	4.2	6.8	10.4	13.9	19.4	25.3	29.4	39.1	48.5	58.5	72.7	93.5
	Rated		ND	1.1	1.7	2.8	3.8	6.1	8.7	11.1	15.9	22.2	26.3	32.9	42.3	50.6	63.0	76.2
	capacity (kVA)		VLD	1.8	3.3	4.3	6.5	9.5	13.7	19.1	24.9	33.3	38.7	51.5	63.6	76.9	95.2	122.6
	, ,	240 V	LD	1.5	2.6	3.9	5.0	8.1	12.5	16.6	23.3	30.3	35.3	47.0	58.2	70.3	87.3	112.2
			ND	1.3	2.1	3.3	4.6	7.3	10.4	13.3	19.1	26.6	31.6	39.5	50.7	60.7	75.7	91.5
	Rated inp	ut	VLD	5.2	9.5	12.4	18.6	27.1	39.3	54.8	71.4	95.2	110.7	147.6	182.1	220.2	272.6	351.2
	current (A		LD	4.4	7.5	11.2	14.3	23.3	35.7	47.6	66.7	86.9	101.2	134.5	166.7	201.2	250.0	321.4
	*1		ND	3.8	6.0	9.5	13.1	20.8	29.8	38.1	54.8	76.2	90.5	113.1	145.2	173.8	216.7	261.9
Input	Rated input AC voltage			Control power supply: Power supply single phase 200 to 240 V/allowable variation range 170 to 264 V, 50 Hz (allowable variation range: 47.5 to 52.5 Hz)/60 Hz (allowable variation range: 57 to 63 Hz)  Main circuit power supply: 3-phase (3-wire) 200 to 240 V/allowable variation range 170 to 264 V, 50 Hz (allowable variation range: 47.5 to 52.5 Hz)/60 Hz (allowable variation range: 57 to 63 Hz)														
	Power supply VLD		2.0	3.6	4.7	7.1	10.3	15.0	20.9	27.2	36.3	42.2	56.3	69.4	83.9	103.9	133.8	
		equipment		1.7	2.9	4.3	5.4	8.9	13.6	18.1	25.4	33.1	38.6	51.3	63.5	76.7	95.3	122.5
	capacity (	(KVA)	ND	1.5	2.3	3.6	5.0	7.9	11.3	14.5	20.9	29.0	34.5	43.1		66.2	82.6	99.8
	-		VLD	0.5 to 1	0.0 kHz													
	requency		LD	0.5 to 1	2.0 kHz													
operatin	ig range *	3	ND	0.5 to 1	6.0 kHz										30   37   153   185   140   169   122   146     146			
Motor st	art torque	*4		200%/0	.3 Hz													
Braking	Regenera	tive bra	aking	Equipped with BRD circuit (with a discharging resistor separately installed)  Regenerative braking unit separately installed										it				
Diaking	Minimum r			50	50	35	35	35	16	10	10	7.5	7.5	5				
Dim	Height (m	ım)		255	255	255	255	255	260	260	260	390	390	390	540	550	550	700
Dimen- sion	Width (m	m)		150	150	150	150	150	210	210	210	245	245	245	300	390	390	480
	Depth (m	m)		140	140	140	140	140	170	170	170	190	190	190	195	250	250	250
Protecti	ve constru	ction		IP20 <b>*</b> 5	/ UL op	en type	•	•	•	•	•			•	•	•		•
Approximate mass (kg)				3	3	3	3	3	6	6	6	10	10	10	22	33	33	47

- \*1. The rated input currents shown in the table are the values when the rated current is output. The values vary depending on impedance on the power supply (wiring, breaker, input reactor option, etc.)
- \*2. The power supply equipment capacities shown in the table are the values when 220 V rated current is output. The values vary depending on impedance on the power supply (wiring, breaker, input reactor option, etc.)
- \*3. The setting of rated values for carrier frequencies [bb101]/[bb201] are internally limited in accordance with the description. Also, it is recommended to set values equivalent to or above (maximum output frequency for driving x10) Hz for the setting of carrier frequencies [bb101]/ [bb201]. Also, in the case of induction motor (IM) control, for items other than those subject to V/f control, it is recommended to set carrier frequency at 2 kHz or more. In the case of synchronous motor (SM)/permanent magnet motor (PMM) control, it is recommended to set carrier frequency at 8 kHz or more.
- \*4. The value of the sensor-less vector control applied to the ND rating in the Standard motor. Torque characteristics may vary depending on the control method and the motor used.
- \*5. Based on self declaration.

#### 3-phase 400-V Class

Very Low Duty (VLD)/Low Duty (LD)/Normal Duty (ND)

·				1			1			1			- ,	1	, ,			, ,			
3	G3RX2-□□			A4007	A4015	A4022	A4037	A4055	A4075	A4110	A4150	A4185	A4220	A4300	A4370	A4450	A4550	B4750	B4900	B411K	B413K
Annlicat	ole motor		VLD	1.5	2.2	3.7	5.5	7.5	11	15	18.5	22	30	37	45	55	75	90	110	132	160
	capacity (I	(W)	LD	1.5	2.2	3.7	5.5	7.5	11	15	18.5	22	30	37	45	55	75	90	110	132	160
			ND	0.75	1.5	2.2	3.7	5.5	7.5	11	15	18.5	22	30	37	45	55	75	90	110	132
	Rated output		VLD	4.1	5.4	8.3	12.6	17.5	25.0	31.0	40.0	47.0	62.0	77.0	93.0	116	147	176	213	252	316
	current (A		LD	3.1	4.8	6.7	11.1	16.0	22.0	29.0	37.0	43.0	57.0	70.0	85.0	105	135	160	195	230	290
			ND	2.5	4.0	5.5	9.2	14.8	19.0	25.0	32.0	39.0	48.0	61.0	75.0	91.0	112	150	180	217	260
	Overload		VLD		60 sec																
	current ra	ting	LD		120% 60 sec / 150% 3 sec																
Outmut			ND		60 sec																
Output	Rated out	put vol			se (3-w	, <i>i</i>		, · · ·	, <u> </u>		, <u> </u>		1	1		1				1	
	400 11	VLD	2.8	3.7	5.8	8.7	12.1	17.3	21.5	27.7	32.6	43.0	53.3	64.4	80.4	101.8	121.9	147.6	174.6	218.9	
	D	400 V	LD	2.1	3.3	4.6	7.7	11.1	15.2	20.1	25.6	29.8	39.5	48.5	58.9	72.7	93.5	110.9	135.1	159.3	200.9
	Rated capacity	ND	1.7	2.8	3.8	6.4	10.3	13.2	17.3	22.2	27.0	33.3	42.3	52.0	63.0	77.6	103.9	124.7	150.3	180.1	
	(kVA)		VLD	3.6	4.7	7.2	10.9	15.2	21.7	26.8	34.6	40.7	53.7	66.7	80.5	100.5	127.3	152.4	184.5	218.2	273.7
	500 V	LD	2.7	4.2	5.8	9.6	13.9	19.1	25.1	32.0	37.2	49.4	60.6	73.6	90.9	116.9	138.6	168.9	199.2	251.1	
			ND	2.2	3.5	4.8	8.0	12.8	16.5	21.7	27.7	33.8	41.6	52.8	65.0	78.8	97.0	129.9	155.9	187.9	225.2
	Rated inp		VLD	4.9	6.4	9.9	15.0	20.8	29.8	36.9	47.6	56.0	73.8	91.7	110.7	138.1	175.0	209.5	253.6	300.0	376.2
	current (A) LD		3.7	5.7	8.0	13.2	19.0	26.2	34.5	44.0	51.2	67.9	83.3	101.2	125.0	160.7	190.5	232.1	273.8	345.2	
			ND	3.0	4.8	6.5	11.0	17.6	22.6	29.8	38.1	46.4	57.1	72.6	89.3	108.3	133.3		214.3	258.3	309.5
Innut	Rated input AC			Control power supply: Power supply single phase 380 to 500 V (allowable variation range 323 to 550 V), 50 Hz (allowable variation range: 47.5 to 52.5 Hz)/60 Hz (allowable variation range: 57 to 63 Hz)																	
Input	voltage			Main circuit power supply: 3-phase (3-wire) 380 to 500 V (allowable variation range) 323 to 550 V, 50 Hz (allowable variation range: 47.5 to 52.5 Hz)/60 Hz (allowable variation range: 57 to 63 Hz)																	
	Power su		VLD	3.7	4.9	7.5	11.4	15.9	22.7	28.1	36.3	42.6	56.3	69.9	84.4	105.2	133.4	159.7	193.2	228.6	286.7
	equipmer capacity (		LD	2.8	4.4	6.1	10.1	14.5	20.0	26.3	33.6	39.0	51.7	63.5	77.1	95.3	122.5	145.2	176.9	208.7	263.1
	<b>*</b> 2	, KVA,	ND	2.3	3.6	5.0	8.3	13.4	17.2	22.7	29.0	35.4	43.5	55.3	68.0	82.6	101.6	136.1	163.3	196.9	235.9
			VLD	0.5 to	10.0 kF	lz												0.5 to	8.0 kHz		
Carrier f	requency		LD	0.5 to	12.0 kF	łz												0.5 to	8.0 kHz		
range w	•		ND	0.5 to	16.0 kH	lz												0.5 to	10.0 kF	lz	
Motor st	art torque	*4	,	200%/	200%/0.3 Hz 180%/0.3 Hz																
Dankina	Regenera	tive bra	aking		ped with a discha					alled)						Regen installe		braking	unit se	eparate	ly
Braking	Minimum r			100	100	100	70	70	35	35	24	24	20	15	15	10	10				
	Height (m	m)		255	255	255	255	260	260	260	390	390	390	540	550	550	550	700	700	740	740
Dimen- sion	Width (mi	n)		150	150	150	150	210	210	210	245	245	245	300	390	390	390	390	390	480	480
51011	Depth (mi	m)		140	140	140	140	170	170	170	190	190	190	195	250	250	250	270	270	270	270
Protectiv	ve constru	ction		IP20 \$	\$5 / UL	open ty	ре											IP00 /	UL ope	n type	
Approxi	mate mass	(kg)		3	3	3	3	6	6	6	8.5	8.5	8.5	22	31	31	31	41	41	53	53
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- \*1. The rated input currents shown in the table are the values when the rated current is output. The values vary depending on impedance on the power supply (wiring, breaker, input reactor option, etc.)
- \*2. The power supply equipment capacities shown in the table are the values when 220 V rated current is output. The values vary depending on impedance on the power supply (wiring, breaker, input reactor option, etc.)
- \*3. The setting of rated values for carrier frequencies [bb101]/[bb201] are internally limited in accordance with the description. Also, it is recommended to set values equivalent to or above (maximum output frequency for driving x10) Hz for the setting of carrier frequencies [bb101]/ [bb201]. Also, in the case of induction motor (IM) control, for items other than those subject to V/f control, it is recommended to set carrier frequency at 2 kHz or more. In the case of synchronous motor (SM)/permanent magnet motor (PMM) control, it is recommended to set carrier frequency at 8 kHz or more.
- \*4. The value of the sensor-less vector control applied to the ND rating in the Standard motor. Torque characteristics may vary depending on the control method and the motor used.
- \*5. Based on self declaration.

## **Function Specifications**

## **Inverter 3G3RX2**

	Item			Specifications					
Control mo	ode the motor)		Sine wave PWM control voltage output	ut (line sine wave modulation)					
Output free	quency range	*1	0.00 to 590.00 Hz						
Frequency	accuracy		Digital command ±0.01% and analog	command ±0.2% (25°C±10°C) against	the maximum frequency				
Frequency	resolution		Digital setting: 0.01 Hz Analog setting: maximum frequency/4 (Ai1 terminal/Ai2 terminal: 12 bit/0 to -	9000 +10 V or 0 to +20 mA, Ai3 terminal 12 b	oit/-10 to +10 V)				
Control mo		ulation) #2	IM	V/f control (fixed torque/reduced torque/free), automatic boost control, IM cascade model sensorless vector control, 0 Hz range sensorless vector control, vector control with sensor.					
(irequency	//voltage calcu	ilation) *2	SM/PMM	Synchronous starting sensorless vector sensorless vector control	tor control, IVMS starting smart				
Speed fluc	tuation *3		±0.5% (during sensorless vector contr	rol)					
Acceleration	on or decelera	tion time	0.00 to 3600.00 sec (linear, S-shaped	, U-shaped, reverse U-shaped, EL-S s	haped)				
Display mo	onitor		Output frequency, output current, outp	out torque, trip history, I/O terminal stat	us, I/O power *4, P-N voltage.				
Starting fu	ınctions		Start after DC braking, frequency colle	ection start, frequency entrainment star	t, reduced voltage start, retry start				
Stopping f	functions		Free-run stop, DC braking after decele adjustment)	eration stop or terminal DC braking (bra	aking power, operating speed				
Stall preve	ention function	1	Overload restraining function, overcur	rent suppression function, overvoltage	suppression function				
Protective	function *5		Undervoltage error, Current detector e voltage error, Instantaneous power fai temperature error, Temperature error,	ilure error, Temperature detector error,	error, Ground fault error, Incoming over Cooling fan rotation speed reduction put open-phase error, Thermistor error,				
Other functions			Manual torque boost, Energy-saving of frequency adjustment, Motor electronic function, External start/end (volume/ration)		nction, Minimum frequency, Carrier possible), Inverter electronic thermal				
		Standard operator keypad	Parameter setting using arrow keys						
		/ External signals *6	Ai1/Ai2 terminal (when changing voltage)  Setting through input of 0 t voltage (input impedance:						
	Fraguenov		Ai1/Ai2 terminal (when changing curre	Setting through input of 0 to 20 mA current (input impedance: 100 $\Omega$ )					
	Frequency setting		Ai3 terminal	Setting through input of -10 to +10 V voltage (input impedance: 10 k $\Omega$ )					
			Multistage speed terminal (use of input terminal function)		15 speed				
			Pulse string input (A/B terminal, use of input terminal fur	32 kHz x 2 at maximum					
		External port	Setting via RS485 serial communication	on (protocol: Modbus-RTU)					
	Normal rotation/	Standard operator keypad	Execution with the RUN /STOP key (normal rotation/reverse rotation can be	, ,,					
	reverse rotation	External signals	Normal rotation operation (FW)/revers available (when an input terminal fund	se rotation (RV) (when an input termina tion is assigned)	I function is assigned) 3-wire input				
Input	Run/stop	External port	<u> </u>	on (protocol: Modbus-RTU (maximum:	115.2 kbps)				
iliput			11 terminals (input of pulse string is a	vailable on terminal A and B)					
	Input terminal function		FW (Normal rotation)/RV (Reverse rotation), CF1-4 (Multistage speed 1-4), SF1-7 (Multistage speed bit 1-7), ADD (Addition of frequency), SCHG (Switching of frequency command), STA (3-wire start)/STP (3-wire stop)/F_R (3-wire normal/reverse), AHD (Retention of analog command), FUP (Increase of speed via remote operation/FDN (Deceleration via remote operation), UDC (Deletion of data via remote operation), F-OP (Forced command switching), SET (Second control), RS (Reset), JG (Jogging), DB (External current braking), 2CH (2-stage acceleration/deceleration), FRS (Free-run stop), EXT (External abnormality), USP (Prevention of restart after restoration of power), CS (Commercial switching), SFT (Soft-lock), BOK (Brake check), OLR (Overload restriction switching), KHC (Clearance of integrated input power), OKHC (Clearance of integrated output power), PID (PID1 disabled), PIDC (PID2 integration reset), SVC1-4 (PID1 multistage target values 1-4), PRO (PID gain switching), PIO (PID output switching), SLEP (SLEEP condition satisfied)/WAKE (WAKE condition satisfied), TL (Torque restriction enabled), TRQ1, 2 (Switching of torque limit 1, 2), PPI (Switching of P/PI control), CAS (Switching of control gain), FOC (Preparatory excitation), ATR (Torque control enabled), TBS (Torque bias enabled), LAC (Cancellation of acceleration/deceleration), MI1-11 (General-purpose input 1-11), PCC (Clearance of pulse counter), ECOM (Start of EzCOM), PRG (Program run), HLD (Acceleration/deceleration stop), REN (Operation permission signal), PLA (Pulse string input A), and PLB (Pulse string input B)						
			input 1-11), PCC (Clearance of pulse	, LAC (Cancellation of acceleration/deccounter), ECOM (Start of EzCOM), PR	G (Program run), HLD (Acceleration/				
	Backup pov	wer supply	input 1-11), PCC (Clearance of pulse	, LAC (Cancellation of acceleration/dec counter), ECOM (Start of EzCOM), PR ermission signal), PLA (Pulse string inp	G (Program run), HLD (Acceleration/				
			input 1-11), PCC (Clearance of pulse deceleration stop), REN (Operation per P+/P-: DC24V input (allowable input v 2 terminals (simultaneous input)	, LAC (Cancellation of acceleration/dec counter), ECOM (Start of EzCOM), PR ermission signal), PLA (Pulse string inp	G (Program run), HLD (Acceleration/ out A), and PLB (Pulse string input B)				

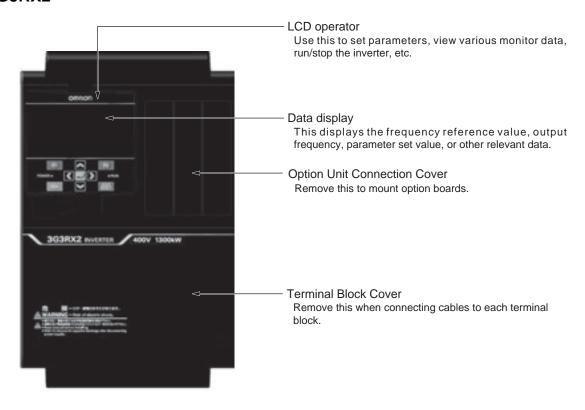
	Item		Specifications					
	Output terminal function	Transistor output 5 terminal, 1a contact	ct relay 1 point, 1c contact relay 1 point					
Output	Relay and alarm relay (16, AL)	RUN (During operation), FA1-5 (Reached signal), IRDY (Operation ready completion), FWR (During normal rotation operation), RVR (During reverse rotation operation), FREF (Frequency command operator keypad), REF (Operation command operator keypad), SETM (Second control under selection), AL (Alarm signal), MJA (Severe failure signal), OTQ (Over torque) *7, IP (During instantaneous power failure), UV (Under insufficient voltage), TRQ (During torque limitation), IPS (During power failure deceleration), RNT (RUN time over), ONT (Power on time over), THM (Electronic thermal warning), THC (Electronic thermal warning), WAC (Capacitor life advance notice), WAF (Fan life advance notice), FR (Operation command signal), OHF (Cooling fin heating advance notice), LOC/LOC2 (Low-current signal), OL/OL2 (Overload advance notice), BRK (Brake release), BER (Brake abnormality), ZS (Zero-speed detection signal), OD/OD2 (PID deviation excessive), FBV/FBV2 (PID feedback comparison), NDc (Communication disconnection), Ai1Dc/Ai2Dc/Ai3Dc (Analog disconnection Ai1/Ai2/Ai3), WCAi1/WCAi2/WCAi3 (Window comparator Ai1/Ai2/Ai3), LOG1-7 (Logical operation result 1-7), MO1-7 (General output 1-7), and OVS (Receiving overvoltage).						
	EDM output terminal	Output for STO diagnosis						
	Monitor output terminal *8	Possible to output through selection fr	om monitor data of parameters					
EMC filter sv	witching *9	Possible to enable the EMC noise filter (switching method is different depending on the model)						
External acc	cess to PC	USB Micro-B						
		ND (normal duty)	-10 to 50°C					
	Ambient temperature *10	LD (low duty)	-10 to 45°C					
		VLD (very low duty)	-10 to 40°C					
Use	Storage temperature *11	-20 to 65°C						
environment	Humidity	20-90%RH (location free of condensa	tion)					
	Vibration *12		(2-A2004 to A2220 / 3G3RX2-A4007 to A4220 (2-A2300 to A2550 / 3G3RX2-A4300 to A413K					
	Use location *13	1000 m altitude or lower (location free	from corrosive gas, oil mist, and dust)					
		Smoothing capacitor 10 years						
Expected Life	fe time	Designed life of cooling fan 10 years (	models equipped with a cooling fan) free from dust					
		Memory element on the control circuit	board					
Applicable s	standards *14	Conformance to UL/cUL standards, E	U Directives and UK legislation, RCM, Functional Safety SIL3/PLe, KC					
Painting cold	or	Black						
Operating, d	lisplay	LCD Operator *15						
Number of o	option slots	3 ports						
Other option	ıs	Braking resistor, AC reactor, DC react	or, noise filter, EtherCAT Communication, PG					

- \*1. The output frequency range depend on the control and motor used. When running the inverter exceeding 60 Hz, check the maximum allowable frequency with the manufacturer of the motor.
- \*2. When the control mode is changed, unless the motor constant is appropriately configured, you cannot obtain the desired starting torque or the inverter may trip.
- \*3. The variable range of motor speed may vary depending on your system or the environment where the motor is used. Please contact us for details.
- \*4. Both the input power and output power are reference values, which are not appropriate for use in calculation of efficiency values, etc. To obtain an accurate value, use an external device.
- \*5. The IGBT error [E030] is generated by the protective function not only for short circuit protection but also when IGBT is damaged. Depending on the operating conditions of the inverter, the overcurrent error [E001] may occur, instead of the IGBT error.
- \*6. At the factory default setting, when voltage and current on Ai1/Ai2 terminal is changed using a switch, with input of voltage at 9.8 V and current at 19.8 mA, the maximum frequency is commanded. To change characteristics, make adjustments using the analog start/end function.
- \*7. The threshold for signal output varies depending on the motor to be combined with the inverter, parameter adjustment, etc.
- \*8. The output data of analog voltage monitor and analog current monitor are reference values for connecting an analog meter. Due to the meter to be connected and variation in analog output circuit, the maximum output value may slightly vary from 10 V or 20 mA. To change characteristics, make adjustments using the Ao1 adjustment and Ao2 adjustment functions. Some monitor data cannot be output.
- \*9. To enable the EMC filter, connect with a power supply grounded at a neutral point. Otherwise, the leakage current may increase.
- \*10. Use the 400 V class inverter at an input voltage of 500 VAC or below. If input voltage exceeds 500 VAC due to fluctuation of power, use the inverter at 40°C or lower ambient temperature.
- **\*11.** The storage temperature is the temperature during transport.
- \*12. To be in accordance with the testing method specified in JIS C 60068-2-6: 2010 (IEC 60068-2-6:2007)
- **\*13.** When the inverter is used in a location at 1000 m or higher altitude, air pressure reduces approximately 1% every 100 m elevation. Perform 1% current der- ating and conduct evaluation for every 100 m elevation.
- \*14. For insulation distance, comply with UL and CE standards
- \*15. When a clock function is used, the optional battery (CR2032, 3 V) is required. When you purchase, this LCD operator does not come with the battery.

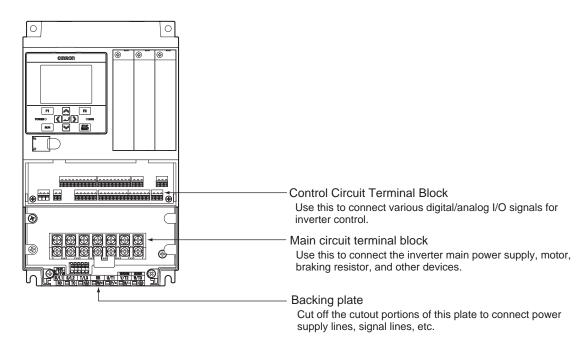
## **Components and Functions**

Note: Example of the 3G3RX2-A2055/A2075/A2110/A4055/A4075/A4110

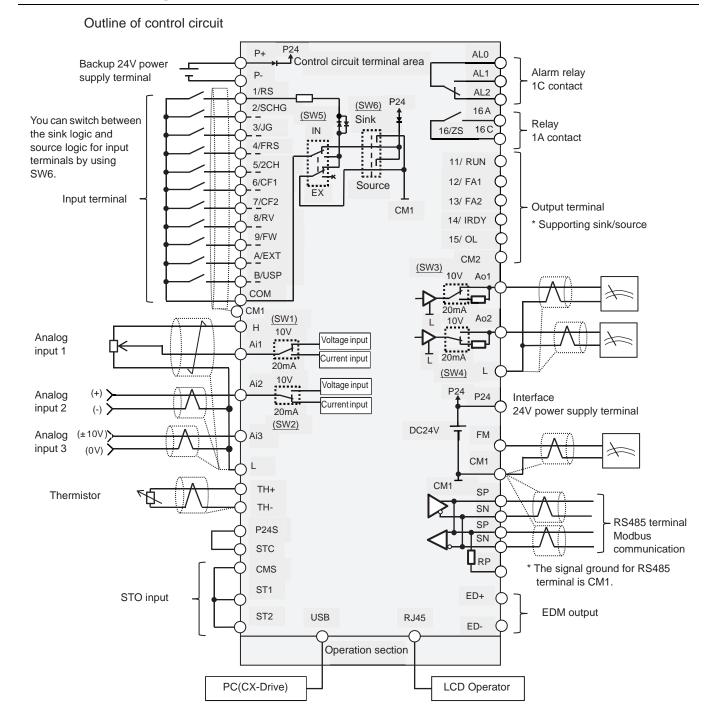
## **Inverter 3G3RX2**



Open the terminal block cover to wire the main circuit terminal block and the control circuit terminal block. Moreover, you can open the Option Unit Connection Cover to mount option boards.



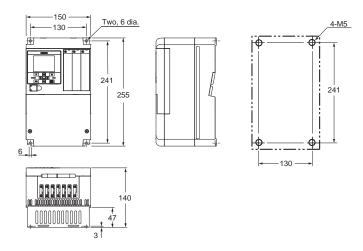
## **Connection Diagram**



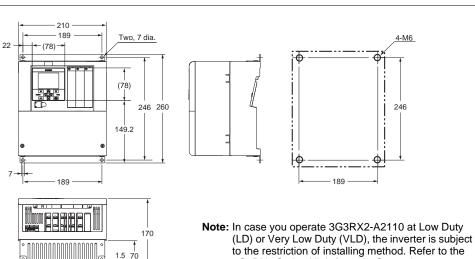
Dimensions (unit: mm)

## **Inverter 3G3RX2**

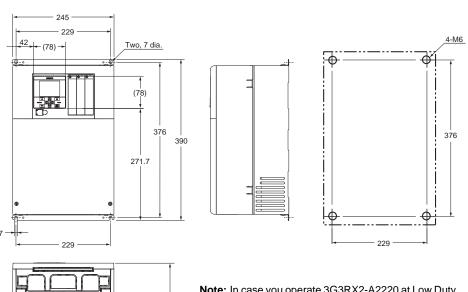
3G3RX2-A2004 3G3RX2-A2007 3G3RX2-A2015 3G3RX2-A2022 3G3RX2-A2037 3G3RX2-A4007 3G3RX2-A4015 3G3RX2-A4022 3G3RX2-A4037

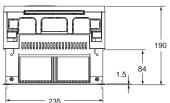


3G3RX2-A2055 3G3RX2-A2075 3G3RX2-A2110 3G3RX2-A4055 3G3RX2-A4075 3G3RX2-A4110



3G3RX2-A2150 3G3RX2-A2185 3G3RX2-A2220 3G3RX2-A4150 3G3RX2-A4185 3G3RX2-A4220

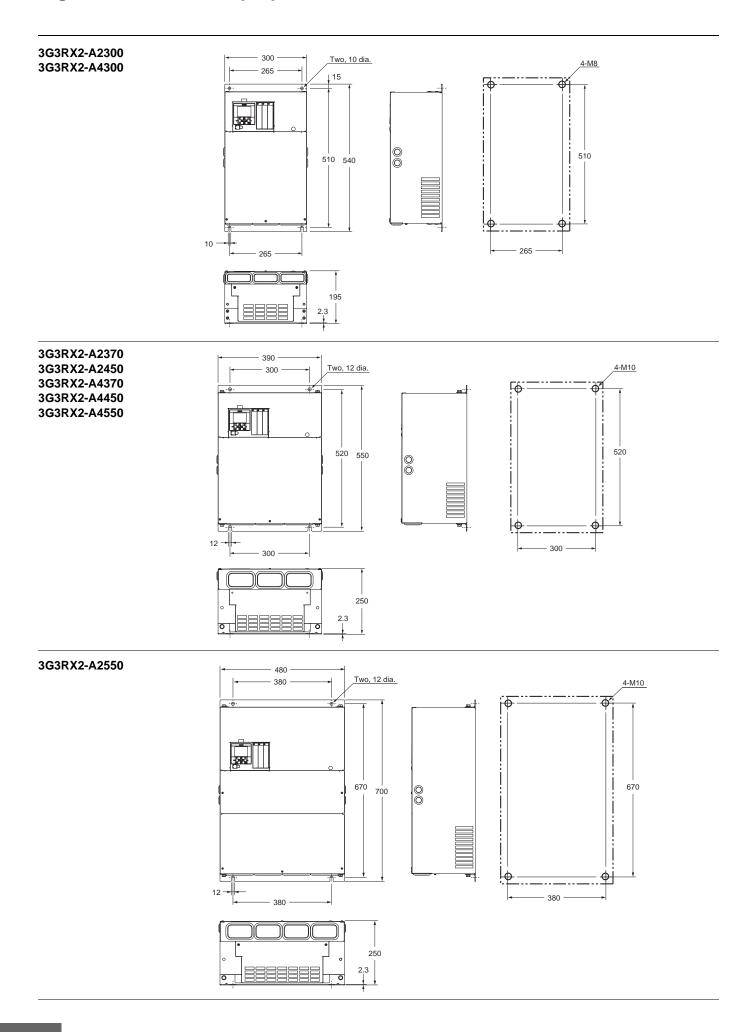




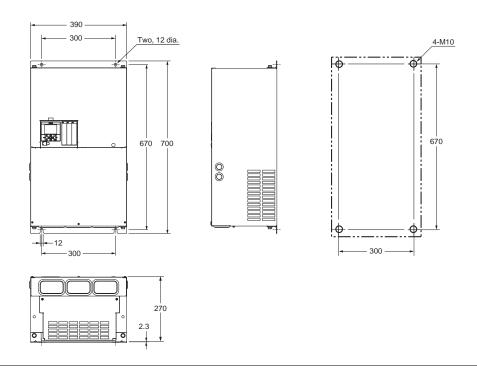
203

Note: In case you operate 3G3RX2-A2220 at Low Duty (LD) or Very Low Duty (VLD), the inverter is subject to the restriction of installing method. Refer to the 3G3RX2 Series High-function General-purpose Inverter User's Manual (Cat.No.1620) for details.

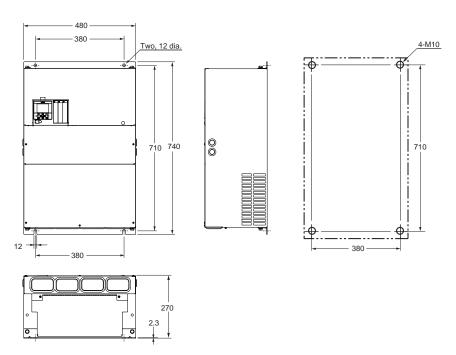
3G3RX2 Series High-function General-purpose Inverter User's Manual (Cat.No.I620) for details.



#### 3G3RX2-B4750 3G3RX2-B4900



#### 3G3RX2-B411K 3G3RX2-B413K



## **Communication Unit**

The EtherCAT Communication Unit is an interface unit. When installed to an RX2 series high-function general-purpose inverter, it provides support for 100-Mbps EtherCAT.

## **Common Specifications**

Item	Specifications
Model	3G3AX-RX2-ECT
Power supply	Supplied from the inverter
Protective structure	Open type (IP20)
Ambient operating temperature	-10 to 50°C
Ambient storage temperature	-20 to 65°C
Ambient operating humidity	20% to 90% (with no condensation)
Vibration *1	5.9 m/s <sup>2</sup> (0.6 G), 10 to 55 Hz
Application environment	Indoors (There should be no corrosive gas, oil mist, or metal dust.)
Weight	100 g max. (Shipping weight: approx. 200 g)
Applicable standards	Conformance to EU Directives and UK legislation, UL/cUL, CSA, KC, RCM, EAC

**<sup>\*1.</sup>** When using the EtherCAT Communication Unit with the inverters listed below, install the unit where it is not subjected to vibration or shock. Vibration or shock can cause communication errors or malfunctions. Applicable models: 3G3RX2-A2300 to A2550, 3G3RX2-A4300 to B413K

## **EtherCAT Communications Specifications**

Item	Specifications						
Communications standard	IEC 61158 Type12, IEC 61800-7 CiA 402 drive profile						
Physical layer	100BASE-TX (IEEE802.3)						
	RJ45 x 2 (shielded type)						
Connector	ECAT IN: EtherCAT input						
	ECAT OUT: EtherCAT output						
Communications media	Category 5 or higher (cable with double, aluminum tape and braided shielding) is recommended.						
Communications distance	Distance between nodes: 100 m max.						
Process data	Fixed PDO mapping						
Frocess data	User PDO mapping						
Mailbox (CoE)	Emergency messages, SDO requests, and SDO responses						
Synchronization mode	FreeRun mode *1						
	L/A IN (Link/Activity IN) x 1						
LED display	L/A OUT (Link/Activity OUT) x 1						
LED display	RUN x 1						
	ERR x 1						
CiA402 drive profile	Velocity mode						

<sup>\*1.</sup> In FreeRun mode, slaves perform I/O processing, i.e., refresh I/O data asynchronously with the communications cycle of the master. The communications cycle is determined by the cycle time of the master. For the communications response time of the EtherCAT Communication Unit, refer to the EtherCAT Communication Unit User's Manual (Cat.No. 1663) for details.

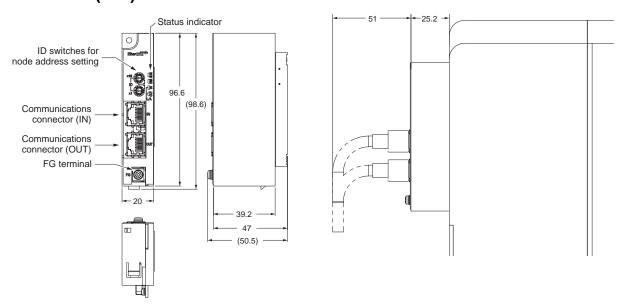
Note that FreeRun mode in the synchronization mode has a different meaning from free-run stop of an Inverter.

#### **Version Information**

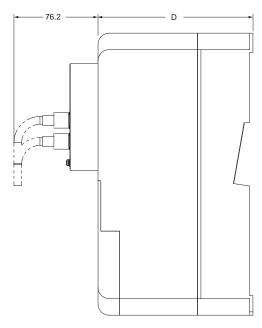
The following table gives the relationship between unit versions of EtherCAT Communication Unit and the corresponding Sysmac Studio versions.

EtherCAT Communication Unit version	Sysmac Studio			
Ver. 1.0 or later	Ver. 1.47 or higher			

## **Dimensions (mm)**



**Note:** For the overall depth when the EtherCAT Communication Unit is installed with an EtherCAT cable connected, add 76.2 mm to the dimension D of the Inverter. The dimension D differs depending on its capacity of the Inverter. Please refer to the manual for the Inverter.

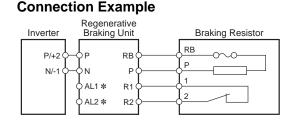


## **Options**

## Regenerative Braking Unit 3G3AX-RBU□□

Used with a Braking Resistor when the deceleration time of the motor is needed to be reduced in the 3G3RX2.





The alarm output terminals for the Regenerative Braking Unit. Provide a circuit to turn off the primary power supply for the Inverter when the temperature relay of the built-in resistor or optional Braking Resistor is activated.

Note: The Braking Resistor (RBA, RBB, RBC) has a built-in thermal fuse. This thermal fuse may blow due to rising temperature after the thermal relay between terminal 1 and terminal 2 issued an alarm. When the fuse blows, replace the resistor and correctly wire the alarm output terminals. If an temperature error is detected, stop the inverter and cool down well before restart.

## **Specifications**

Built-in Resistance Type (3G3AX-RBU21/-RBU22/-RBU41)

	Class	3-phase 2	00-V class	3-phase 400-V class
	Model name (3G3AX-)	RBU21	RBU22	RBU41 *1
Connection res	istance	17 Ω min.	17 Ω min.	$34~\Omega$ min.
Operating volta	ge ON/OFF	ON: 362.5 ± 5 V, OFF: 355 ± 5 V (-5% or -10% setting available)		ON: 725 ± 5 V, OFF: 710 ± 5 V (-5% or -10% setting available)
Operation indic	ation	LED ON (Lit)		
Parallel interloc	cking operation function *2	5 units max.		
	Internal resistance	120 W, 180 Ω	120 W, 20 Ω	120 W, 180 Ω x 2 in series
	Allowable consecutive ON time	10 s max.	0.5 s max.	10 s max.
Built-in resistor	Allowable operation cycle	Cycle 1/10 (ON for 10 s, OFF for 90 s)	Cycle 1/80 (ON for 0.5 s, OFF for 40 s)	Cycle 1/10 (ON for 10 s, OFF for 90 s)
	Power consumption	Instantaneous 0.73 kW Short-time rating 120 W	Instantaneous 6.6 kW Short-time rating 120 W	Instantaneous 1.46 kW Short-time rating 240 W
Protective function	Built-in resistor overheat protection	Recover Built-in temperature fuse (recover	Ć 200 mA (R load), 12 V DC 500 m	
	Ambient temperature	−10 to 50°C		
Onevetina	Ambient storage temperature	−20 to 65°C		
Operating environment	Ambient operating humidity	20% to 90% (with no condensation)		
o	Vibration	5.9 m/s <sup>2</sup> (0.6G) 10 to 55 Hz		
	Location	At a maximum altitude of 1,000 m (	without corrosive gases or dust)	
Paint color		Munselle 5Y7/1 (cooling fan: alumir	ium ground color)	

- \*1. To use the braking resistor (Model: 3G3AX-RAB/RBB/RBC) for the 400-V class regenerative braking unit, be sure to remove the built-in resistor and connect two resistors of the same model in series. Using a 400-V class regenerative braking unit with only a single braking resistor connected may cause damage to the braking resistor.
- \*2. Use DIP switches to set the number of connected units.
- \*3. The built-in resistor has a thermal fuse. If the alarm terminals are not connected, the fuse may blow out in order to prevent the resistor from burning due to overheating. If the fuse blows out, the built-in resistor must be replaced.

#### **Specifications**

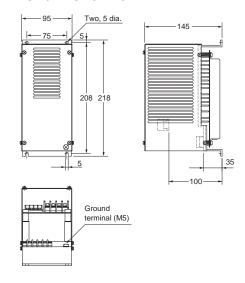
External resistor type (3G3AX-RBU23/-RBU24/-RBU42/-RBU43)

•	Class	3-phase	200-V class	3-phas	se 400-V class			
	Model name (3G3AX-)	RBU23	RBU24	RBU42 *1	RBU43 *1			
	Continuous operation	$6\Omega$ min.	4 Ω min.	24 Ω min.	12 Ω min.			
Discharge resistance	Short-time/ operation Allowable operation cycle/ Continuous ON time	4 Ω min. 1/5 2 min	2 Ω min. 1/5 2 min	10 Ω min. 1/10 10 s	6 Ω min. 1/5 2 min			
Operating volta	age ON/OFF	ON: 362.5 ± 5 V, OFF: 35 (-5% or -10% setting av						
Operation indic	cation	LED ON (Lit)						
Maximum num	ber of units operating in parallel *2	2 units max.						
Protective functions	Internal power module overheat protection	Built-in relay specification  Cooling fin temperature Rating of contact  Minimum load	e Relay operates at ap	d), 36 V DĆ 2 A (R load)				
	Ambient temperature	−10 to 50°C						
0	Ambient storage temperature	−20 to 65°C		nin. $\begin{array}{c} 10~\Omega \text{ min.} \\ 1/10 \\ 10~s \\ \end{array}$ $\begin{array}{c} 6~\Omega \\ 1/5 \\ 2~\text{mi} \\ \end{array}$ ON: $725\pm5~\text{V}, \text{ OFF: } 710\pm5~\text{V} \\ (-5\%~\text{or } -10\%~\text{setting available} \\ \end{array}$ by operates at approximately $100^{\circ}\text{C}$ or higher. V AC 3 A (R load), $36~\text{V DC } 2~\text{A (R load)} \\ \text{DC } 50~\text{mA (R load)} \\ \text{Dn)} \\ \text{n (without corrosive gases or dust)}$				
Operating environment	Ambient operating humidity	20% to 90% (with no con	densation)					
environment	Vibration	4.9 m/s <sup>2</sup> (0.5G) 10 to 55 l	Hz					
	Location	At a maximum altitude of	1,000 m (without corros	ive gases or dust)				
Paint color		Munselle 5Y7/1 (cooling to	an: aluminum ground co	olor)				

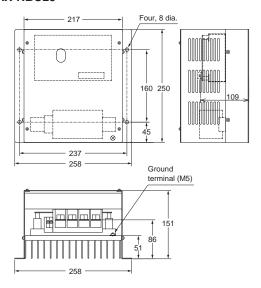
- \*1. To use the braking resistor (3G3AX-RAB/RBB/RBC) for the 400-V class regenerative braking unit, be sure to remove the built-in resistor and connect two resistors of the same model in series. Using a 400-V class regenerative braking unit with only a single braking resistor connected may cause damage to the braking resistor.
- \*2. Use DIP switches to set the number of connected units.

## **Dimensions (Unit: mm)**

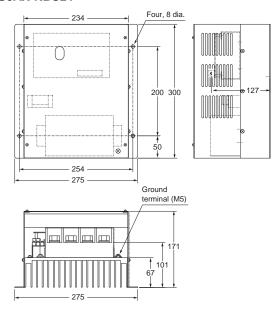
#### 3G3AX-RBU21/-RBU22/-RBU41



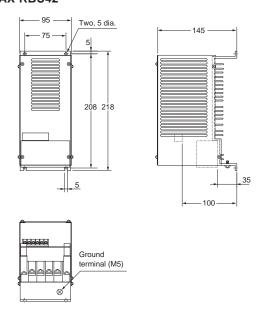
#### 3G3AX-RBU23



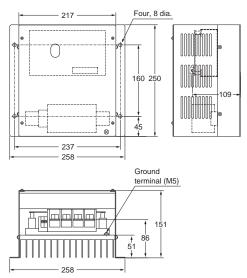
#### 3G3AX-RBU24



#### 3G3AX-RBU42

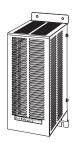


## 3G3AX-RBU43



## Braking Resistor 3G3AX-RBA/-RBB/-RBC□□□□□

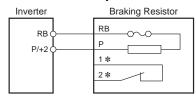
Consumes the regenerative motor energy with a resistor to reduce deceleration time.







### **Connection Example**



\*The alarm output terminals for the Braking Resistor. Provide a circuit to turn off the primary power supply for the Inverter when the temperature relay of the Braking Resistor is activated.

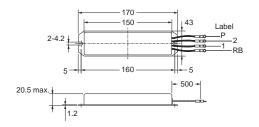
## **Specifications**

	Model	(		ict type BA□□□□	1)	(		ard type BB□□□□	)				
		1201	1202	1203	1204	2001	2002	3001	4001	4001	6001	12001	
Resistance	Capacity	120 W				200 W		300 W	400 W	400 W	600 W	1200 W	
Resistance	Resistance (Ω)	180	100	50	35	180	100	50	35	50	35	17	
Allowable braki	ngfrequency (%)	5	2.5	1.5	1.0	10	7.5	7.5	7.5		10		
Allowable conti	nuousbraking time (s)	20	12	5	3		30		20		50 35 17 10 10		
Weight (kg)			0.	27		0.	97	1.68	2.85	2.5 3.6 6.5			
Fault detection	function	Minimum Normally	current: 5 ON (NC c	mA, ontact)	acity: 240 \	/ AC 2 A n ossible) *	nax.)			Normally ON Contact capa	N (NC contact) acity:240 V AC	3 A (R load),	
	Ambient operating temperature	-10 to 50°C											
	Ambient storage temperature	-20 to 65	5°C										
General specifications	Ambient operating humidity	20% to 9	0% (RH) v	vith no cor	ndensation						600 W 35 10 10 3.6 mperature relay, ON (NC contact) apacity:240 V AC		
	Vibration	5.9 m/s (	0.6 G) 10	to 55 Hz C	omplies w	ith JISC09	11						
	Location	At a max	imum altiti	ude of 1,00	00 m (with	out corrosi	ve gases	or dust)					
	Cooling method	Self-cooli	ing										

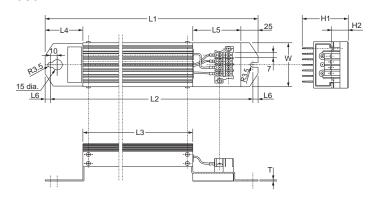
<sup>\*</sup>Built-in resistors are equipped with thermal fuses. If the alarm is not connected, the fuse may blow to prevent burnout due to overheating. If the fuse blows, the built-in resistor will need to be replaced.

## **Dimensions (Unit: mm)**

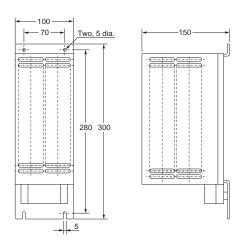
### 3G3AX-RBA



### 3G3AX-RBB



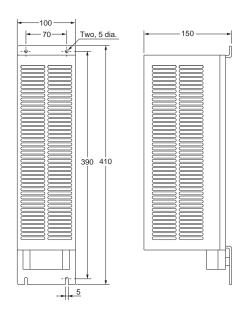
3G3	AX-R	BC40	001



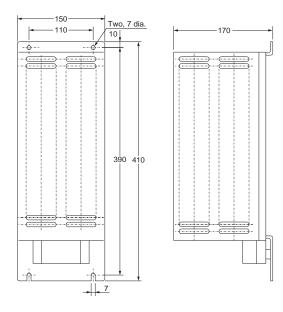
Model	Dimensions (mm)									
Wodei	L1	L2	L3	L4	L5	L6				
3G3AX-RBB2001	310	295	160	55	70	7.5				
3G3AX-RBB2002	310	295	160	55	70	7.5				
3G3AX-RBB3001	470	455	320	55	70	7.5				
3G3AX-RBB4001	435	422	300	50	60	6.5				

Model	Dir	nensi	ons (m	nm)	Weight	Terminal	
Wodei	H1	H2	W	Т	[kg]	screws	
3G3AX-RBB2001	67	12	64	1.6	0.97		
3G3AX-RBB2002	67	12	64	1.6	0.97	M3.5	
3G3AX-RBB3001	67	12	64	1.6	1.68	UIJ.J	
3G3AX-RBB4001	94	15	76	2	2.85		

### 3G3AX-RBC6001



### 3G3AX-RBC12001



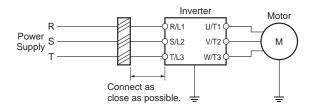
## Radio Noise Filter 3G3AX-ZCL□

Connected to the inverter input/output cables to reduce noise coming into the inverter from the power supply line and noise flowing from the inverter into the power supply line.





#### **Connection Example**



Note 1: Wind each of three phase wires in the same direction.

2: Can be used on both the input and output sides of the Inverter.

## Specifications 3G3AX-ZCL1

Applicable		200 V	class			400 V	class		
Inverter	Inp	out	out	put	Inp	out	output		
capacity (kW)	Quan- tity	No. of turns	Quan- tity	No. of turns	Quan- tity	No. of turns	Quan- tity	No. of turns	
0.2	1	4	1	4	1	4	1	4	
0.4	1	4	1	4	1	4	1	4	
0.75	1	4	1	4	1	4	1	4	
1.5	1	4	1	4	1	4	1	4	
2.2	1	4	1	4	1	4	1	4	
3.0	1	4	1	4	1	4	1	4	
3.7	1	4	1	4	1	4	1	4	
4.0	1	4	1	4	1	4	1	4	
5.5	1	4	1	4	1	4	1	4	
7.5	1	4	1	4	1	4	1	4	
11	1	3	1	3	1	4	1	4	
15	1	2	1	2	1	4	1	4	

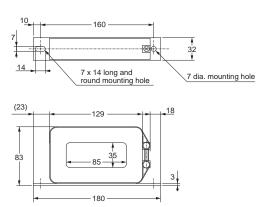
## Specifications 3G3AX-ZCL2

Applicable		200 V	class			400 V	class	
Inverter	Inp	out	out	put	Inp	out	out	put
capacity (kW)	Quan- tity	No. of turns						
0.1	1	4	1	4	1	4	1	4
0.2	1	4	1	4	1	4	1	4
0.4	1	4	1	4	1	4	1	4
0.75	1	4	1	4	1	4	1	4
1.5	1	4	1	4	1	4	1	4
2.2	1	4	1	4	1	4	1	4
3.0	1	4	1	4	1	4	1	4
3.7	1	4	1	4	1	4	1	4
4.0	1	4	1	4	1	4	1	4
5.5	1	4	1	4	1	4	1	4
7.5	1	4	1	4	1	4	1	4

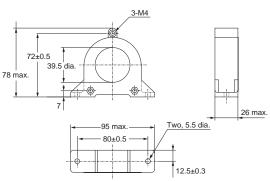
Note: When the inverter is used in the LD or VLD mode, select a radio noise filter according to the capacity of the used motor that is more than one size larger than in the ND mode.

## **Dimensions (Unit: mm)**

#### 3G3AX-ZCL1



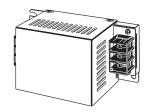
#### 3G3AX-ZCL2

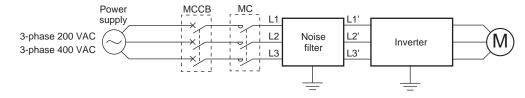


## Input Noise Filter 3G3AX-NFI□□

Reduces noise coming into the inverter from the power supply line and noise flowing from the inverter into the power supply line. Connect as close to the Inverter as possible.

## **Connection Example**





## **Specifications**

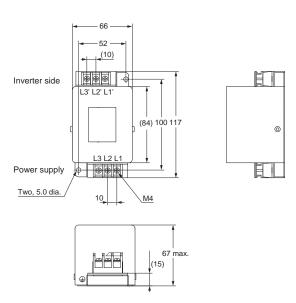
		Inver	ter				Input noise	e filter specific	ations	
Voltage class	Max. applicable motor capacity [kW]	Model	Load specification selection	Max. applicable motor capacity [kW]	Rated input current [A]	Model	Max. input voltage	Rated input current (at 50°C) [A]	Heat generation [W]	Leakage current (at 60 Hz)
			ND	0.4	3.3					
	0.4	3G3RX2-A2004	LD	0.75	3.9	3G3AX-NFI21		6	3	
			VLD	0.75	3.9	303AX-111 121			3	
			ND	0.75	5.5					
	0.75	3G3RX2-A2007	LD	1.5	7.2					
			VLD	1.5	7.2	3G3AX-NFI22		10	4	
			ND	1.5	8.3					
	1.5	3G3RX2-A2015	LD	2.2	10.8					
			VLD	2.2	10.8					
			ND	2.2	12	3G3AX-NFI23		20	6	
	2.2		3G3AA-NFIZ3		20	0				
			VLD	3.7	13.9					
			ND	3.7	18					
	3.7	3G3RX2-A2037	LD	5.5	23					
			VLD	5.5	23	3G3AX-NFI24		30	9	
	5.5		ND	5.5	26					
		3G3RX2-A2055	LD	7.5	37					Ī
			VLD	7.5	37	3G3AX-NFI25		40	12	
			ND	7.5	35					
	7.5	3G3RX2-A2075	LD	11	48					-
			VLD	11	48	3G3AX-NFI26		60	17	1 5 m 1
		3G3RX2-A2110	ND	11	51		250 VAC +10%			1.5 mA max.
200-V	11		LD	15	64					(250 VAC)
class			VLD	15	64	3G3AX-NFI27		80	21	, , ,
			ND	15	70					
	15	3G3RX2-A2150	LD	18.5	80					
			VLD	18.5	80	3G3AX-NFI28		100	23	
			ND	18.5	84					
	18.5	3G3RX2-A2185	LD	22	94					
			VLD	22	94					
			ND	22	105					
	22	3G3RX2-A2220	LD	30	120	3G3AX-NFI29		150	45	
		000.0.127.12220	VLD	30	120					
			ND	30	133					
	30	3G3RX2-A2300	LD	37	150		-			
	00	00011712 712000	VLD	37	150	3G3AX-NFI2A		200	50	
			ND	37	160	000,000		200	00	
	37	3G3RX2-A2370	LD	45	186					
	37	3031012 112310	VLD	45	186	3G3AX-NFI2B		250	68	
			ND	45	200	303/1X 141 12B		250	00	
	45	3G3RX2-A2450	LD	55	240		-			1
	45	303NAZ-AZ430	VLD	55	240	3G3AX-NFI2C		300	56	
						JGJAA-INFIZU		300	50	
	E E	3C3DV3 A3550	ND	55 75	242					1
	55	3G3RX2-A2550	LD	75 75	280					
	1	303K/2-A2330	VLD	75	280					

		Inver	ter				Input noise	e filter specific	ations	
Voltage class	Max. applicable motor capacity [kW]	Model	Load specification selection	Max. applicable motor capacity [kW]	Rated input current [A]	Model	Max. input voltage	Rated input current (at 50°C) [A]	Heat generation [W]	Leakage current (at 60 Hz)
			ND	0.75	2.8					
	0.75	3G3RX2-A4007	LD	1.5	4.3					
			VLD	1.5	4.3					
			ND	1.5	4.2	3G3AX-NFI41		7	2	
	1.5	3G3RX2-A4015	LD	2.2	5.9					
			VLD	2.2	5.9					
			ND	2.2	5.8					
	2.2	3G3RX2-A4022	LD	3.7	8.1					
			VLD	3.7	8.1	3G3AX-NFI42		10	4	
			ND	3.7	9.8					
		3G3RX2-A4037	LD	5.5	13.3					
			VLD	5.5	13.3					
			ND	5.5	15	3G3AX-NFI43		20	6	
		3G3RX2-A4055	LD	7.5	20			20	Ü	
			VLD	7.5	20					
			ND	7.5	21					
	7.5	3G3RX2-A4075	LD	11	24					
			VLD	11	24	3G3AX-NFI44		30	9	
		3G3RX2-A4110	ND	11	28	3G3AX-NFI45				7.5 1
	11		LD	15	32		480 VAC			7.5 mA max.
400-V			VLD	15	32		+10%	40	12	(480 VAC)
class			ND	15	35					
	15	3G3RX2-A4150	LD	18.5	41					
			VLD	18.5	41	3G3AX-NFI46		50	15	
			ND	18.5	42					
	18.5	3G3RX2-A4185	LD	22	47					
			VLD	22	47	3G3AX-NFI47		60	17	
			ND	22	53					
	22	3G3RX2-A4220	LD	30	63					
			VLD	30	63	3G3AX-NFI48		80	21	
			ND	30	64					
	30	3G3RX2-A4300	LD	37	77					
			VLD	37	77	3G3AX-NFI49		100	23	
			ND	37	83					
	37	3G3RX2-A4370	LD	45	94					
			VLD	45	94					
			ND	45	100	3G3AX-NFI4A		150	45	
	45	3G3RX2-A4450	LD	55	116	500,0,111117A		130	.0	
			VLD	55	116					
			ND	55	121					
	55	3G3RX2-A4550	LD	75	149					
	55	3G3RX2-A4550	VLD	75	149					

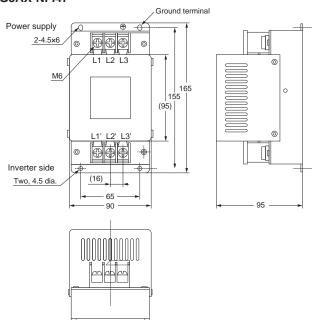
## **Dimensions (Unit: mm)**

Model	Case, enclosure rating	Terminal size	Wire diameter	Weight [kg]
3G3AX-NFI21	Plastic, IP00	M4	1.25 mm <sup>2</sup>	0.5
3G3AX-NFI22	Plastic, IP00	M4	2 mm <sup>2</sup>	0.6
3G3AX-NFI23	Plastic, IP00	M4	2 mm², 3.5 mm²	0.7
3G3AX-NFI24	Plastic, IP00	M4	5.5 mm <sup>2</sup>	0.8
3G3AX-NFI25	Plastic, IP00	M5	8 mm <sup>2</sup>	1.4
3G3AX-NFI26	Plastic, IP00	M5	14 mm²	1.8
3G3AX-NFI27	Metal, IP00	M6	22 mm <sup>2</sup>	3.6
3G3AX-NFI28	Metal, IP00	M8	30 mm <sup>2</sup>	4.6
3G3AX-NFI29	Metal, IP00	M8	38 mm², 60 mm²	9.0
3G3AX-NFI2A	Metal, IP00	M10	100 mm <sup>2</sup> or 38 mm <sup>2</sup> , 2 wires parallel	16
3G3AX-NFI2B	Metal, IP00	M10	100 mm² or 38 mm², 2 wires parallel	16
3G3AX-NFI2C	Metal, IP00	M10	150 mm² or 60 mm², 2 wires parallel	23
3G3AX-NFI41	Plastic, IP00	M4	1.25 mm², 2 mm²	0.7
3G3AX-NFI42	Plastic, IP00	M4	2 mm <sup>2</sup>	0.7
3G3AX-NFI43	Plastic, IP00	M4	2 mm², 3.5 mm²	0.7
3G3AX-NFI44	Plastic, IP00	M4	5.5 mm <sup>2</sup>	0.8
3G3AX-NFI45	Plastic, IP00	M5	8 mm <sup>2</sup>	1.4
3G3AX-NFI46	Plastic, IP00	M5	14 mm²	1.6
3G3AX-NFI47	Plastic, IP00	M5	14 mm <sup>2</sup>	1.8
3G3AX-NFI48	Metal, IP00	M6	22 mm <sup>2</sup>	3.6
3G3AX-NFI49	Metal, IP00	M8	38 mm <sup>2</sup>	4.6
3G3AX-NFI4A	Metal, IP00	M8	38 mm², 60 mm²	9.0

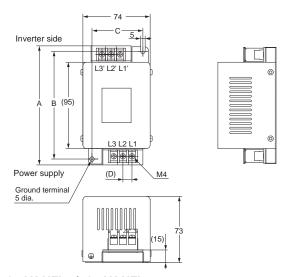
#### 3G3AX-NFI21 3G3AX-NFI22



#### 3G3AX-NFI25/3G3AX-NFI26 3G3AX-NFI45/3G3AX-NFI46 3G3AX-NFI47

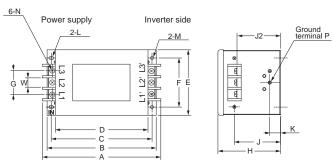


#### 3G3AX-NFI23/3G3AX-NFI24 3G3AX-NFI41/3G3AX-NFI42 3G3AX-NFI43/3G3AX-NFI44



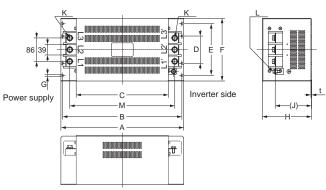
Model		Dimension	ons (mm)	
Wodel	Α	В	С	D
3G3AX-NFI23	128	118	56	10
3G3AX-NFI24	144	130	56	11
3G3AX-NFI41	144	130	56	11
3G3AX-NFI42	144	130	56	11
3G3AX-NFI43	144	130	56	11
3G3AX-NFI44	144	130	56	11

#### 3G3AX-NFI27/3G3AX-NFI28 3G3AX-NFI29/3G3AX-NFI48 3G3AX-NFI49/3G3AX-NFI4A



Model								Di	mensic	ns (mn	n)					
Wodei	Α	В	С	D	Е	F	G	Н	J	J2	K	L	M	N	Р	W
3G3AX-NFI27	217	200	185	170	120	90	44	115	85	82	20	R2.75, Length 7	5.5 dia.	M6	M4	17
3G3AX-NFI28	254	230	215	200	150	120	57	115	80	75	30	R3.75, Length 8	6.5 dia.	M8	M6	23
3G3AX-NFI29	314	300	280	260	200	170	57	130	90	85	35	R3.75, Length 8	6.5 dia.	M8	M6	23
3G3AX-NFI48	217	200	185	170	120	90	44	115	85	85	20	R2.75, Length 7	5.5 dia.	M6	M4	17
3G3AX-NFI49	254	230	215	200	150	120	57	115	80	75	30	R3.75, Length 8	6.5 dia.	M8	M6	23
3G3AX-NFI4A	314	300	280	260	200	170	57	130	90	85	35	R3.75, Length 8	6.5 dia.	M8	M6	23

### 3G3AX-NFI2A/3G3AX-NFI2B 3G3AX-NFI2C



Model	Dimensions (mm)												
Wodei	Α	В	С	D	E	F	G	Н	J	K	L	M	N
3G3AX-NFI2A	450	430	338	100	190	230	7	180	(133)	M10	M8	385	1.0
3G3AX-NFI2B	450	430	330	100	190	230	,	100	(133)	IVITO	IVIO	303	1.0
3G3AX-NFI2C	500	475	400		160	200	12	180	(133)	M10	M8	445	1.2

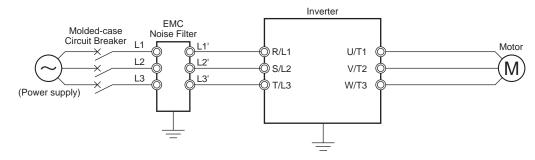
## **EMC** Noise Filter 3G3AX-EFI□□□

Separately installed option used to comply with the EC's EMC Directives. Select a filter appropriate for the Inverter model.

Although an EMC Noise Filter is built into the RX2, it may be necessary to provide another EMC Noise Filter when the cable between the Motor and the Inverter is long.



## **Connection Example**



## **Specifications**

		Inver	ter				EMC n	oise filter s	pecification	s	
Voltage class	Max. applicable motor capacity [kW]	Model	Load specification selection	Max. applicable motor capacity [kW]	Rated input current [A]	Model	Max. input voltage	Rated input current [A]	Heat generation [W]	Leakage current (at 480 VAC 60 Hz)	Class
			ND	0.4	3.3						
	0.4	3G3RX2-A2004	LD	0.75	3.9	20247 55144		7	4	450 4	
			VLD	0.75	3.9	3G3AX-EFI41		7	4	150 mA max.	
			ND	0.75	5.5						
	0.75	3G3RX2-A2007	LD	1.5	7.2						
			VLD	1.5	7.2	3G3AX-EFI42		10	4	150 mA max.	
			ND	1.5	8.3						
	1.5	3G3RX2-A2015	LD	2.2	10.8						
			VLD	2.2	10.8						
			ND	2.2	12	3G3AX-EFI43		20	8	170 mA max.	
	2.2	3G3RX2-A2022	LD	3.7	13.9	3G3AA-EF143		20	0	170 ma max.	
			VLD	3.7	13.9						
			ND	3.7	18						
	3.7	3G3RX2-A2037	LD	5.5	23						
			VLD	5.5	23	3G3AX-EFI44		30	9	170 mA max.	
			ND	5.5	26						
	5.5	3G3RX2-A2055	LD	7.5	37						
			VLD	7.5	37	3G3AX-EFI45		40	15	170 mA max.	
			ND	7.5	35		480 VAC +10%				Α
200-V class	7.5	3G3RX2-A2075	LD	11	48		+1076		15		1
Class			VLD	11	48	3G3AX-EFI47		60		250 mA max.	
			ND	11	51						
	11	3G3RX2-A2110	LD	15	64						
			VLD	15	64	3G3AX-EFI48		80	21	250 mA max.	
			ND	15	70						
	15	3G3RX2-A2150	LD	18.5	80						
			VLD	18.5	80	3G3AX-EFI49		100	23	250 mA max.	
			ND	18.5	84						
	18.5	3G3RX2-A2185	LD	22	94						
			VLD	22	94						
			ND	22	105						
	22	3G3RX2-A2220	LD	30	120	3G3AX-EFI4A		150	45	250 mA max.	
			VLD	30	120						
	30 3G3RX2-		ND	30	133						
		3G3RX2-A2300	LD	37	150		1				
			VLD	37	150	3G3AX-EFI4B		200	50	250 mA max.	
			ND	37	160						
	37	3G3RX2-A2370	LD	45	186						
			VLD	45	186						

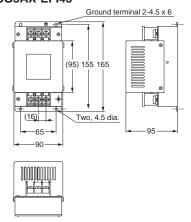
		Inver	ter				EMC n	oise filter s <sub>l</sub>	pecification	ıs	
Voltage class	Max. applicable motor capacity [kW]	Model	Load specification selection	Max. applicable motor capacity [kW]	Rated input current [A]	Model	Max. input voltage	Rated input current [A]	Heat generation [W]	Leakage current (at 480 VAC 60 Hz)	Class
			ND	0.75	2.8						
	0.75	3G3RX2-A4007	LD	1.5	4.3						
			VLD	1.5	4.3						
			ND	1.5	4.2	3G3AX-EFI41		7	4	150 mA max.	
	1.5	3G3RX2-A4015	LD	2.2	5.9						
			VLD	2.2	5.9						
			ND	2.2	5.8						
	2.2	3G3RX2-A4022	LD	3.7	8.1						
			VLD	3.7	8.1	3G3AX-EFI42		10	4	150 mA max.	
			ND	3.7	9.8						
	3.7	3G3RX2-A4037	LD	5.5	13.3						
			VLD	5.5	13.3						
			ND	5.5	15						
	5.5	3G3RX2-A4055	LD	7.5	20	3G3AX-EFI43		20	8	170 mA max.	
			VLD	7.5	20						
			ND	7.5	21						
	7.5	3G3RX2-A4075	LD	11	24						
			VLD	11	24	3G3AX-EFI44		30	9	170 mA max.	
			ND	11	28						
	11	3G3RX2-A4110	LD	15	32		-				
			VLD	15	32	3G3AX-EFI45		40	15	170 mA max.	
			ND	15	35	000,012,110					
	15	3G3RX2-A4150	LD	18.5	41		480 VAC				
400-V		00010/12711100	VLD	18.5	41	3G3AX-EFI46	+10%	50	15	250 mA max.	Α
duu-v class			ND	18.5	42	303/1X E1 140		30	10	200 111/11114.	
	18.5	3G3RX2-A4185	LD	22	47		-				
	10.5	303NAZ-A4103	VLD	22	47	3G3AX-EFI47		60	15	250 mA max.	
			ND	22	53	3G3AX-L1 147		00	13	250 IIIA IIIAX.	
	22	3G3RX2-A4220	LD	30	63		-				
	22	3G3KX2-A4220	VLD	30	63	3G3AX-EFI48		80	21	250 mA max.	
			ND	30	64	3G3AX-L1 140		00	21	250 IIIA IIIAX.	
	30	3G3RX2-A4300	LD	37	77		_				
	30	3G3RAZ-A4300	VLD	37	77	3G3AX-EFI49		100	23	250 mA max.	
						3G3AX-EF149		100	23	250 MA Max.	
	27	2C2DV2 A4270	ND	37	83						
	37	3G3RX2-A4370	LD	45	94						
			VLD	45	94						
	45	0000000 44450	ND	45	100	3G3AX-EFI4A		150	45	250 mA max.	
	45	3G3RX2-A4450	LD	55	116						
			VLD	55	116						
			ND	55	121						
	55	3G3RX2-A4550	LD	75	149						
			VLD	75	149						
			ND	75	164	3G3AX-EFI4B		200	50	250 mA max.	
	75	3G3RX2-B4750	LD	90	176		3 20				
			VLD	90	176						
			ND	90	194						
	90	3G3RX2-B4900	LD	110	199						
			VLD	110	199						

## **Dimensions (Unit: mm)**

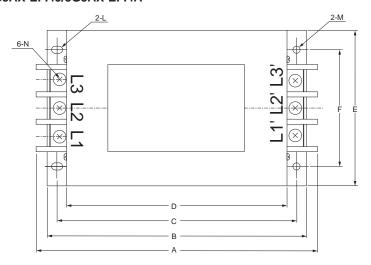
Model	Case, enclosure rating	Screw size	Wire size	Weight [kg]
3G3AX-EFI41			1.25 mm², 2 mm²	0.7
3G3AX-EFI42		M4	2 mm <sup>2</sup>	0.7
3G3AX-EFI43	Plastic, IP00		2 mm <sup>2</sup> , 3.5 mm <sup>2</sup>	1.0
3G3AX-EFI44		M5	5.5 mm <sup>2</sup>	1.3
3G3AX-EFI45			8 mm <sup>2</sup>	1.4
3G3AX-EFI46			14 mm <sup>2</sup>	2.9
3G3AX-EFI47		M6	14 mm <sup>2</sup>	3.0
3G3AX-EFI48	Matal ID00		22 mm <sup>2</sup>	3.6
3G3AX-EFI49	Metal, IP00	MO	30 mm², 38 mm²	4.3
3G3AX-EFI4A		M8	38 mm², 60 mm²	9.0
3G3AX-EFI4B		M10	100 mm <sup>2</sup> or 38 mm <sup>2</sup> , 2 wires parallel	16.0

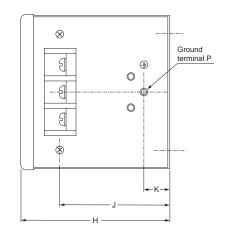
# 3G3AX-EFI41 3G3AX-EFI42

#### 3G3AX-EFI43/3G3AX-EFI44 3G3AX-EFI45



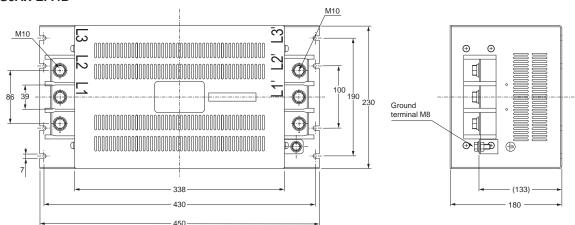
#### 3G3AX-EFI46/3G3AX-EFI47/3G3AX-EFI48 3G3AX-EFI49/3G3AX-EFI4A





Model						Dim	ensions [ı	mm]					
Wodei	Α	В	С	D	E	F	Н	J	K	L	М	N	Р
3G3AX-EF146													
3G3AX-EF147	217	220	185	170	120	90	115	85	20	R2.75, Length 7	5.5 dia.	M6	M4
3G3AX-EF148													
3G3AX-EF149	254	230	215	200	150	120	115	80	30	R3.25, Length 8	6.5 dia.	M8	M6
3G3AX-EF14A	314	300	280	260	200	170	130	90	35	R3.25, Length 8	6.5 dia.	M8	M6

#### 3G3AX-EFI4B

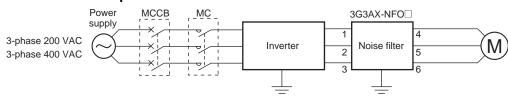


## Output Noise Filter 3G3AX-NFO□□

Reduces noise generated by the Inverter. Connect as close to the Inverter as possible.

## **Connection Example**



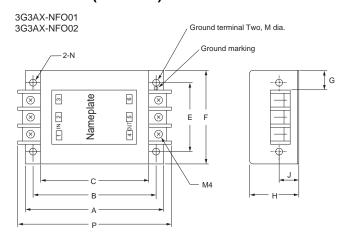


## **Specifications**

		Inve	erter			Outpu	t noise filte	r specification	s
Voltage class	Max. applicable motor capacity [kW]	Model	Load specification selection	Max. applicable motor capacity [kW]	Rated input current [A]	Model	Rated voltage	Rated input current [A]	Weight [kg]
			ND	0.4	3.0				
	0.4	3G3RX2-A2004	LD	0.75	3.7	2C2AV NEO01		6	0.7
			VLD	0.75	3.7	3G3AX-NFO01		6	0.7
			ND	0.75	5.0				
	0.75	3G3RX2-A2007	LD	1.5	6.3				
			VLD	1.5	6.3				
			ND	1.5	7.5	2024 V NEO22		40	0.0
	1.5	3G3RX2-A2015	LD	2.2	9.4	3G3AX-NFO02		12	0.9
			VLD	2.2	9.4				
			ND	2.2	10.5				
	2.2	3G3RX2-A2022	LD	3.7	12				
			VLD	3.7	12				
			ND	3.7	16.5				
	3.7	3G3RX2-A2037	LD	5.5	19.6	3G3AX-NFO03		25	2.1
			VLD	5.5	19.6				
			ND	5.5	24				
	5.5	3G3RX2-A2055	LD	7.5	30				
			VLD	7.5	30				
			ND	7.5	32		500 VAC		
.00-V	7.5	3G3RX2-A2075	LD	11	44	3G3AX-NFO04		50	3.7
lass			VLD	11	44				
			ND	11	46				
	11	3G3RX2-A2110	LD	15	58				
			VLD	15	58	3G3AX-NFO05		75	5.7
			ND	15	64				
	15	3G3RX2-A2150	LD	18.5	73				
			VLD	18.5	73				
			ND	18.5	76				
	18.5	3G3RX2-A2185	LD	22	85	3G3AX-NFO06		100	8.4
			VLD	22	85				
			ND	22	95				
	22	3G3RX2-A2220	LD	30	113				
			VLD	30	113				
			ND	30	121				
	30	3G3RX2-A2300	LD	37	140	3G3AX-NFO07		150	9.0
		300.0.27.2000	VLD	37	140				
			ND	37	145				
	37	3G3RX2-A2370	LD	45	169				
	37	303KAZ-AZ370	VLD	45	169				

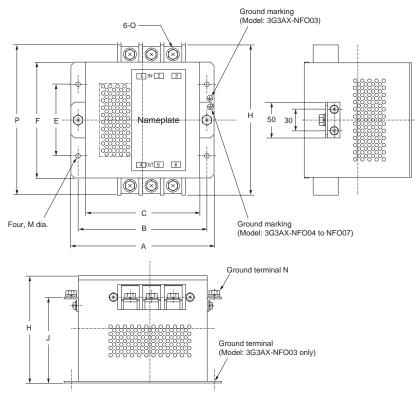
		Inve	erter			Output	t noise filte	r specification	S
Voltage class	Max. applicable motor capacity [kW]	Model	Load specification selection	Max. applicable motor capacity [kW]	Rated input current [A]	Model	Rated voltage	Rated input current [A]	Weight [kg]
			ND	0.75	2.5				
	0.75	3G3RX2-A4007	LD	1.5	3.1				
			VLD	1.5	3.1				
			ND	1.5	3.8	3G3AX-NFO01		6	0.7
	1.5	3G3RX2-A4015	LD	2.2	4.8				
			VLD	2.2	4.8				
			ND	2.2	5.3				
	2.2	3G3RX2-A4022	LD	3.7	6.7				
			VLD	3.7	6.7	3G3AX-NFO02		12	0.9
			ND	3.7	9.0				
	3.7	3G3RX2-A4037	LD	5.5	11.1				
			VLD	5.5	11.1				
			ND	5.5	14				
	5.5	3G3RX2-A4055	LD	7.5	16				
			VLD	7.5	16	3G3AX-NFO03		25	2.1
			ND	7.5	19				
	7.5	3G3RX2-A4075	LD	11	22				
	7.0	0001012711070	VLD	11	22				
			ND	11	25				
	11	3G3RX2-A4110	LD	15	29				
		30310A2-A4110	VLD	15	29				
			ND	15	32		500 VAC		
400-V	15	3G3RX2-A4150	LD	18.5	37		300 VAC		
class	15	3031(A2-A4130	VLD	18.5	37	3G3AX-NFO04		50	3.7
			ND		38	3G3AX-N1 O04		30	3.7
	40.5	2C2DV2 A440E	LD	18.5 22	43				
	18.5	3G3RX2-A4185							
			VLD	22	43				
	00	0000000 44000	ND	22	48		-		
	22	3G3RX2-A4220	LD	30	57				
			VLD	30	57				
	0.0	000000	ND	30	58	3G3AX-NFO05		75	5.7
	30	3G3RX2-A4300	LD	37	70				
			VLD	37	70				
			ND	37	75				
	37	3G3RX2-A4370	LD	45	85				
			VLD	45	85	3G3AX-NFO06		100	8.4
			ND	45	91				
	45	3G3RX2-A4450	LD	55	105				
			VLD	55	105				
			ND	55	112	3G3AX-NFO07		150	9.0
	55	3G3RX2-A4550	LD	75	135	300/07-NI 00/		130	5.0
			VLD	75	135				
			ND	75	149				
	75	3G3RX2-B4750	LD	90	160				
			VLD	90	160				

## **Dimensions (Unit: mm)**



Model						Dimensi	ons [mm	]			
Wiodei	Α	В	С	E	F	G	Н	J	M	Р	N
3G3AX-NFO01	140	125	110	70	95	22	50	20	4.5	156	2-R2.25 Length 6
3G3AX-NFO02	160	145	130	80	110	30	70	25	5.5	176	2-R2.75 Length 7

3G3AX-NFO03/3G3AX-NFO04/3G3AX-NFO05 3G3AX-NFO06/3G3AX-NFO07

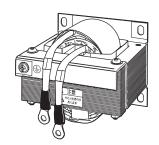


Model					Dim	ensions [	mm]				
Wodei	Α	В	С	E	F	Н	J	М	N	0	Р
3G3AX-NFO03	160	145	130	80	112	120		6.5 dia.		M4	154
3G3AX-NFO04	200	180	160	100	162	150	120	6.5 dia.	M5	M5	210
3G3AX-NFO05	220	200	180	100	182	170	140	6.5 dia.	M6	M6	230
3G3AX-NFO06	220	200	180	100	182	170	140	6.5 dia.	M8	M8	237
3G3AX-NFO07	240	220	200	150	202	170	140	6.5 dia.	M8	M8	257

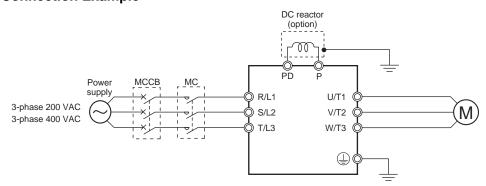
## **DC** Reactor 3G3AX-DL□□□□

Used to suppress harmonic current generated from the Inverter.

Suppresses harmonic current better than the AC Reactor and can be used with the AC Reactor.



## **Connection Example**



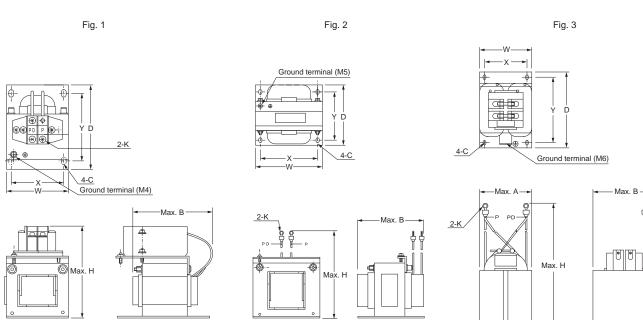
## **Specifications**

		Inver	ter				DC reac	tor specificat	ions	
Voltage class	Max. applicable motor capacity [kW]	Model	Load specification selection	Max. applicable motor capacity [kW]	Rated input current [A]	Model	Inductance [mH]	Heat generation [W]	Operating ambient temperature /humidity	Location
			ND	0.4	3.3	3G3AX-DL2004	10.7	8		
	0.4	3G3RX2-A2004	LD	0.75	3.9					
			VLD	0.75	3.9	3G3AX-DL2007	6.75	15		
•			ND	0.75	5.5					
	0.75	3G3RX2-A2007	LD	1.5	7.2					
			VLD	1.5	7.2	3G3AX-DL2015	3.51	25		
			ND	1.5	8.3					
	1.5	3G3RX2-A2015	LD	2.2	10.8					
			VLD	2.2	10.8	3G3AX-DL2022	2.51	35		
			ND	2.2	12					
	2.2	3G3RX2-A2022	LD	3.7	13.9					
			VLD	3.7	13.9	3G3AX-DL2037	1.60	45		
			ND	3.7	18					
	3.7	3G3RX2-A2037	LD	5.5	23					
			VLD	5.5	23	3G3AX-DL2055	1.11	55		
			ND	5.5	26					
	5.5	3G3RX2-A2055	LD	7.5	37					
			VLD	7.5	37	3G3AX-DL2075	0.84	95		A +
		0000000	ND	7.5	35					At an altitude of
	7.5	3G3RX2-A2075	LD	11	48					1,000 m
			VLD	11	48	3G3AX-DL2110	0.59	80	-10 to 50°C	max.;
200-V	44	202DV0 40440	ND	11	51				20% to 90%	indoors (without
class	11	3G3RX2-A2110	LD	15	64	2024 V DI 2452	0.44	405		corrosive
			VLD	15	64 70	3G3AX-DL2150	0.44	135		gases or
	45	2C2DV2 A2450	ND	15						dust)
	15	3G3RX2-A2150	LD VLD	18.5 18.5	80 80					
			ND	18.5	84					
	18.5	3G3RX2-A2185	LD	22	94	3G3AX-DL2220	0.30	200		
	10.5	3G3KAZ-AZ163	VLD	22	94					
			ND	22	105					
	22	3G3RX2-A2220	LD	30	120				_	
		3031772 772220	VLD	30	120	3G3AX-DL2300	0.23	220		
			ND	30	133	000/1/( 1/2/2000	0.20	220		
	30	3G3RX2-A2300	LD	37	150					
		00011712 712000	VLD	37	150	3G3AX-DL2370	0.19	275		
ŀ			ND	37	160	200.0.00	3.10	_,0		
	37	3G3RX2-A2370	LD	45	186				_	
			VLD	45	186	3G3AX-DL2450	0.16	335		
			ND	45	200	30				
	45	3G3RX2-A2450	LD	55	240				1	
			VLD	55	240	3G3AX-DL2550	0.13	360		
-			ND	55	242					
		3G3RX2-A2550	LD	75	280		<del> </del>			
	55	3G3KAZ-AZ330		10						

		Inver	ter				DC reac	tor specificat	ions	
Voltage class	Max. applicable motor capacity [kW]	Model	Load specification selection	Max. applicable motor capacity [kW]	Rated input current [A]	Model	Inductance [mH]	Heat generation [W]	Operating ambient temperature /humidity	Location
			ND	0.75	2.8	3G3AX-DL4007	27.0	15		
	0.75	3G3RX2-A4007	LD	1.5	4.3					
			VLD	1.5	4.3	3G3AX-DL4015	14.0	25		
			ND	1.5	4.2					
	1.5	3G3RX2-A4015	LD	2.2	5.9					
			VLD	2.2	5.9	3G3AX-DL4022	10.1	35		
			ND	2.2	5.8					
	2.2	3G3RX2-A4022	LD	3.7	8.1					
			VLD	3.7	8.1	3G3AX-DL4037	6.4	45		
			ND	3.7	9.8					
	3.7	3G3RX2-A4037	LD	5.5	13.3					
			VLD	5.5	13.3	3G3AX-DL4055	4.41	55		
			ND	5.5	15					
	5.5	3G3RX2-A4055	LD	7.5	20					
			VLD	7.5	20	3G3AX-DL4075	3.35	95		
			ND	7.5	21					
	7.5	3G3RX2-A4075	LD	11	24					At an
			VLD	11	24	3G3AX-DL4110	2.33	80		altitude o
			ND	11	28					1,000 m max.;
	11	3G3RX2-A4110	LD	15	32				-10 to 50°C	indoors
400-V class			VLD	15	32	3G3AX-DL4150	1.75	135	20% to 90%	(without
Jiass			ND	15	35					corrosive gases or
	15	3G3RX2-A4150	LD	18.5	41					dust)
			VLD	18.5	41					,
	40.5	000DV0 A440F	ND	18.5	42 47	3G3AX-DL4220	1.20	200		
	18.5	3G3RX2-A4185	LD	22						
			VLD ND	22 22	47 53					
	22	2C2DV2 A4220	LD		63					
	22	3G3RX2-A4220	VLD	30 30	63	2024 V DI 4200	0.00	220		
			ND ND	30	64	3G3AX-DL4300	0.92	230		
	30	3G3RX2-A4300	LD	37	77					
	30	JGJNAZ-A4300	VLD	37	77	3G3AX-DL4370	0.74	275		
			ND ND	37	83	JG3AA-DL43/U	0.74	210		
	37	3G3RX2-A4370	LD	45	94				-	
	57	333171Z-74370	VLD	45	94	3G3AX-DL4450	0.61	340		
			ND	45	100	000/07/024400	0.01	0-10		
	45	3G3RX2-A4450	LD	55	116				+	
	70	00017/27/14400	VLD	55	116	3G3AX-DL4550	0.5	400		
			ND	55	121	3307 IX DE4000	0.0	100		
	55	3G3RX2-A4550	LD	75	149					
	55	33317.2714000	VLD	75	149					

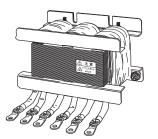
## **Dimensions (Unit: mm)**

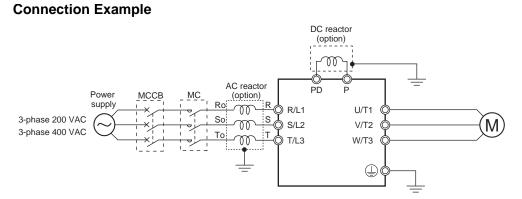
Inverter		Fig.	Applicable				Dime	nsions	[mm]				Weight	Standard
input power supply	Model	No.	motor capacity [kW]	w	D	Н	Α	В	Х	Υ	С	K	[kg]	applicable wire
	3G3AX-DL2002		0.2	66	90	98		85	56	72	5.2×8	M4	0.8	1.25 mm <sup>2</sup> min.
	3G3AX-DL2004		0.4	66	90	98		95	56	72	5.2×8	M4	1.0	1.25 mm <sup>2</sup> min.
	3G3AX-DL2007	F: 4	0.75	66	90	98		105	56	72	5.2×8	M4	1.3	2 mm² min.
	3G3AX-DL2015	Fig. 1	1.5	66	90	98		115	56	72	5.2×8	M4	1.6	2 mm² min.
	3G3AX-DL2022		2.2	86	100	116		105	71	80	6×9	M4	2.1	2 mm <sup>2</sup> min.
	3G3AX-DL2037		3.7	86	100	118		120	71	80	6×9	M4	2.6	3.5 mm <sup>2</sup> min.
	3G3AX-DL2055		5.5	111	100	210		110	95	80	7×11	M5	3.6	8 mm² min.
3/1-phase 200 VAC	3G3AX-DL2075	F: 0	7.5	111	100	212		120	95	80	7×11	M6	3.9	14 mm <sup>2</sup> min.
200 1710	3G3AX-DL2110	Fig. 2	11	146	120	252		110	124	96	7×11	M6	6.5	22 mm² min.
	3G3AX-DL2150		15	146	120	256		120	124	96	7×11	M8	7.0	38 mm² min.
	3G3AX-DL2220		18.5, 22	120	175	356	140	145	98	151	7×11	M8	9.0	60 mm <sup>2</sup> min.
	3G3AX-DL2300		30	120	175	386	155	150	98	151	7×11	M8	13.0	38 mm² x 2 min.
	3G3AX-DL2370	Fig. 3	37	120	175	390	155	150	98	151	7×11	M10	13.5	38 mm² x 2 min.
	3G3AX-DL2450		45	160	190	420	180	150	120	168	7×11	M10	19.0	60 mm <sup>2</sup> x 2 min.
	3G3AX-DL2550		55	160	190	424	180	180	120	168	7×11	M12	24.0	80 mm <sup>2</sup> x 2 min.
	3G3AX-DL4007		0.75	66	90	98		95	56	72	5.2×8	M4	1.1	1.25 mm <sup>2</sup> min.
	3G3AX-DL4015		1.5	66	90	98		115	56	72	5.2×8	M4	1.6	2 mm² min.
3-phase	3G3AX-DL4022	Fin 4	2.2	86	100	116		105	71	80	6×9	M4	2.1	2 mm² min.
400 VAC	3G3AX-DL4037	Fig. 1	3.7	86	100	116		120	71	80	6×9	M4	2.6	2 mm² min.
	3G3AX-DL4055		5.5	111	100	138		110	95	80	7×11	M4	3.6	3.5 mm <sup>2</sup> min.
	3G3AX-DL4075		7.5	111	100	138		115	95	80	7×11	M4	3.9	3.5 mm <sup>2</sup> min.
	3G3AX-DL4110	Fia 0	11	146	120	250		105	124	96	7×11	M5	5.2	5.5 mm <sup>2</sup> min.
	3G3AX-DL4150	Fig. 2	15	146	120	252		120	124	96	7×11	M6	7.0	14 mm² min.
	3G3AX-DL4220		18.5, 22	120	175	352	140	145	98	151	7×11	M6	9.5	22 mm² min.
3-phase 400 VAC	3G3AX-DL4300		30	120	175	356	140	145	98	151	7×11	M8	9.5	30 mm² min.
.50 17.0	3G3AX-DL4370	Fig. 3	37	120	175	386	155	150	98	151	7×11	M8	13.5	38 mm² min.
	3G3AX-DL4450		45	160	190	416	180	145	120	168	7×11	M8	16.5	60 mm² min.
	3G3AX-DL4550	1	55	160	190	416	190	170	120	168	7×11	M8	23.0	38 mm² x 2 min.



## **AC Reactor 3G3AX-AL**□□□□

Connect the AC Reactor if the capacity of the power supply is much larger than that of the Inverter or the power factor is required to be improved.





## **Specifications**

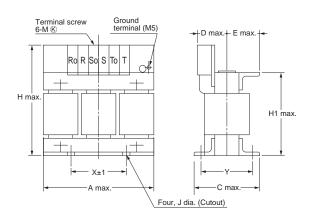
		Inver	ter				AC reac	tor specificat	ions	
Voltage class	Max. applicable motor capacity [kW]	Model	Load specification selection	Max. applicable motor capacity [kW]	Rated input current [A]	Model	Inductance [mH]	Heat generation [W]	Operating ambient temperature/ humidity	Location
			ND	0.4	3.3					
	0.4	3G3RX2-A2004	LD	0.75	3.9					
			VLD	0.75	3.9					
			ND	0.75	5.5	3G3AX-AL2025	2.8	12		
	0.75	3G3RX2-A2007	LD	1.5	7.2					
			VLD	1.5	7.2					
			ND	1.5	8.3					
	1.5	3G3RX2-A2015	LD	2.2	10.8					
			VLD	2.2	10.8					
			ND	2.2	12	3G3AX-AL2055	0.88	25		
	2.2	3G3RX2-A2022	LD	3.7	13.9					
			VLD	3.7	13.9					
			ND	3.7	18					
	3.7	3G3RX2-A2037	LD	5.5	23					
			VLD	5.5	23					
			ND	5.5	26	3G3AX-AL2110	0.35	50		
	5.5	3G3RX2-A2055	LD	7.5	37					
			VLD	7.5	37					
			ND	7.5	35					At an altitude of
	7.5	3G3RX2-A2075	LD	11	48					1,000 m
			VLD	11	48				-10 to 50°C	max.;
200-V			ND	11	51	3G3AX-AL2220	0.18	50	20% to 90%	indoors (without
lass	11	3G3RX2-A2110	LD	15	64					corrosive
			VLD	15	64					gases or
			ND	15	70					dust)
	15	3G3RX2-A2150	LD	18.5	80					
			VLD	18.5	80					
			ND	18.5	84	3G3AX-AL2330	0.09	85		
	18.5	3G3RX2-A2185	LD	22	94					
			VLD	22	94					
			ND	22	105				4	
	22	3G3RX2-A2220	LD	30	120					
			VLD	30	120					
			ND	30	133	3G3AX-AL2500	0.071	95		
	30	3G3RX2-A2300	LD	37	150					
			VLD	37	150					
	07	0000000 40070	ND	37	160					
	37	3G3RX2-A2370	LD	45	186					
			VLD	45	186	4				
		0000000	ND	45	200	3G3AX-AL2750	0.046	100		
	45	3G3RX2-A2450	LD	55	240					
			VLD	55	240	1				
			ND	55	242					
	55	3G3RX2-A2550	LD	75	280					
			VLD	75	280				<u> </u>	

		Inver	ter				AC reac	tor specificat	ions	
Voltage class	Max. applicable motor capacity [kW]	Model	Load specification selection	Max. applicable motor capacity [kW]	Rated input current [A]	Model	Inductance [mH]	Heat generation [W]	Operating ambient temperature/ humidity	Location
			ND	0.75	2.8					
	0.75	3G3RX2-A4007	LD	1.5	4.3	3G3AX-AL4025	7.7	12		
			VLD	1.5	4.3	3G3AX-AL4023	7.7	12		
			ND	1.5	4.2					
	1.5	3G3RX2-A4015	LD	2.2	5.9					
			VLD	2.2	5.9					
			ND	2.2	5.8	3G3AX-AL4055	3.5	25		
	2.2	3G3RX2-A4022	LD	3.7	8.1					
			VLD	3.7	8.1					
			ND	3.7	9.8					
	3.7	3G3RX2-A4037	LD	5.5	13.3	_				
			VLD	5.5	13.3	_				
			ND	5.5	15	3G3AX-AL4110	1.3	50		
	5.5	3G3RX2-A4055	LD	7.5	20	_				
			VLD	7.5	20	1				
	7.5	202DV2 4407E	ND LD	7.5	21					
	7.5	3G3RX2-A4075	VLD	11 11	24	1				At an
			ND	11	28	<u> </u>				altitude of 1,000 m
	11	3G3RX2-A4110	LD	15	32	3G3AX-AL4220	0.74	60	40.4 5000	max.;
400-V	11	3G3KX2-A4110	VLD	15	32	1			-10 to 50°C 20% to 90%	indoors
class			ND	15	35					(without corrosive
	15	3G3RX2-A4150	LD	18.5	41					gases or
	10	0001012711100	VLD	18.5	41					dust)
			ND	18.5	42	1				
	18.5	3G3RX2-A4185	LD	22	47	3G3AX-AL4330	0.36	90		
			VLD	22	47	1				
			ND	22	53	1				
	22	3G3RX2-A4220	LD	30	63				1	
			VLD	30	63	†				
			ND	30	64	2024 \ 41 4500	0.00	05		
	30	3G3RX2-A4300	LD	37	77	3G3AX-AL4500	0.29	95		
			VLD	37	77	1				
			ND	37	83					
	37	3G3RX2-A4370	LD	45	94		50 0.19			
			VLD	45	94					
			ND	45	100	3G3AX-AL4750		100		
	45	3G3RX2-A4450	LD	55	116	3G3AA-AL4750	0.19	100		
			VLD	55	116					
			ND	55	121					
	55	3G3RX2-A4550	LD	75	149					
			VLD	75	149					

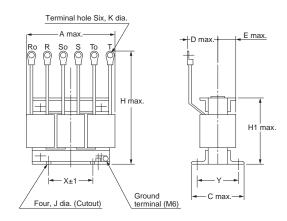
## **Dimensions (Unit: mm)**

Inverter input		Applicable					Dime	ensions	[mm]					Weight
power supply	Model	motor capacity [kW]	Α	С	D	E	н	H1	Х	Y	J	K	w	[kg]
	3G3AX-AL2025	0.2 to 1.5	120	82	60	40	150	94	50	67	6	4.0	9.5	2.8
	3G3AX-AL2055	2.2, 3.7	120	98	60	40	150	94	50	75	6	4.0	9.5	4.0
	3G3AX-AL2110	5.5, 7.5	150	103	70	55	170	108	60	80	6	5.3	12.0	5.0
3-phase 200 VAC	3G3AX-AL2220	11, 15	180	113	75	55	190	140	90	90	6	8.4	16.5	10.0
	3G3AX-AL2330	18.5, 22	180	113	85	60	230	140	125	90	6	8.4	22.0	11.0
	3G3AX-AL2500	30, 37	260	113	85	60	290	202	100	90	7	8.4	27.0	19.0
	3G3AX-AL2750	45, 55	260	144	110	80	290	207	125	112	7	8.4	28.5	25.0
	3G3AX-AL4025	0.4 to 1.5	130	82	60	40	150	94	50	67	6	4	9.5	2.7
	3G3AX-AL4055	2.2, 3.7	130	98	60	40	150	94	50	75	6	5	12.5	4.0
	3G3AX-AL4110	5.5, 7.5	150	116	75	55	170	106	60	98	6	5	12.5	6.0
3-phase 400 VAC	3G3AX-AL4220	11, 15	180	103	75	55	190	140	100	80	6	5.3	12.0	10.0
	3G3AX-AL4330	18.5, 22	180	123	85	60	230	140	100	100	6	6.4	16.5	11.5
	3G3AX-AL4500	30, 37	260	113	85	60	290	202	100	90	7	8.4	22.0	19.0
	3G3AX-AL4750	45, 55	260	146	110	80	290	207	125	112	7	8.4	22.0	25.0

#### 3G3AX-AL2025/3G3AX-AL2055/ 3G3AX-AL4025/3G3AX-AL4055/3G3AX-AL4110



3G3AX-AL2110/3G3AX-AL2220/3G3AX-AL2330 3G3AX-AL2500/3G3AX-AL2750/3G3AX-AL4220 3G3AX-AL4330/3G3AX-AL4500/3G3AX-AL4750



## PG Option Unit 3G3AX-RX2-PG01

The PG Option Unit is an optional unit for the 3G3RX2 Series Inverter. With this unit, you can realize highly accurate system operation with minimum speed fluctuation, and position control via pulse train position command input by detecting the rotation speed of the motor with an encoder and using the data for feedback.

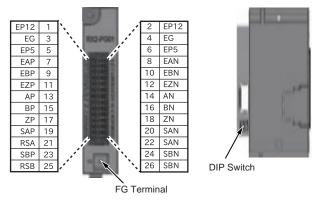


## **Specifications**

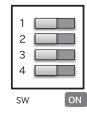
	Item		Specifications					
Model		3G3AX-RX2-P0	G01					
Dimension (width × I	ons neight × depth)	20.5 × 98.0 × 7	0.0 mm					
Weight		170 g						
	Ambient operating temperature	-10 to 50°C						
	Ambient operating humidity	20 to 90% RH	With no icing or condensation					
Environ ment	Storage temperature	-20 to 65°C						
	Vibration resistance	5.9 m/s <sup>2</sup> (0.6G)	, 10 to 55 Hz					
	Protective structure	IP00						
Encoder	feedback	Standard encoder pulse number: 1024 pulse/r     Max. input pulse number : 200k pulse/s						
Position	command	Max. input pulse number : 200k pulse/s						
Protectio	n function		le disconnection Error nit Connection Error					

<sup>\*</sup>The storage temperature is the temperature during transportation.

## **Terminal Arrangement and DIP Switch Setting**



## **Setting the DIP Switch**



Slide to the left to turn the switch OFF, and slide to the right to turn the switch ON.

Switch No.	Settings		
1	ON	Encoder phase A / B, disconnection detection enabled	
	OFF	Encoder phase A / B, disconnection detection disabled	
2	ON	Encoder phase Z, disconnection detection enabled	
	OFF	Encoder phase Z, disconnection detection disabled	
3	ON	Do not change	
	OFF		
4	ON	Do not obonico	
	OFF	Do not change	

Note: All switches are set to OFF as the default setting.

## Wire size and recommended rod terminal shape

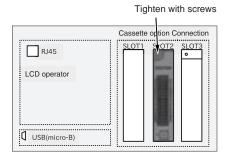
Wire size mm² (AWG)	L1 [mm]	L2 [mm]	d dia. [mm]	D dia. [mm]
0.25 (24)	10.0	14.5	0.8	2.0
0.34 (22)	10.0	14.5	0.8	2.0
0.5 (20)	10.0	16.0	1.1	2.5
0.75 (18)	10.0	16.0	1.3	3.4



## **Terminal Functions**

Terminal name		Terminal	Functions			
		symbol	Tunctions	Common terminal	Electric specifications	
Input terminal	Pulse train position command input	SAP SAN SBP SBN RSA RSB	<ul> <li>Pulse train input procedure         MD0: 90° phase difference pulse         MD1: Forward/Reverse signal, pulse train         MD2: Forward pulse/Reverse pulse Mode settings is made in the pulse train         mode selection (ob-11).</li> <li>RSA: Termination resistor ON/OFF terminal between SAP and SAN</li> <li>RSB: Termination resistor ON/OFF terminal between SBP and SBN</li> <li>Termination resistor settings         Built-in termination resistor: 150 Ω, switch between enabled and disabled with         the wiring         RSA, RSB terminals released: Built-in termination resistor disabled         RSA-SAN short-circuit, RSB-SBN short-circuit: Built-in termination resistor         enabled</li> </ul>		5V DC receiver input (RS-422 compliance)	
	Encoder signal input	EAP EAN EBP EBN EZP EZN	A, B, Z: Rotary encoder signal input		Photo coupler input (Corresponds to the 5V DC line driver output type rotary encoder)	
Output terminal	Encoder signal output	AP AN BP BN ZP ZN	Output the encoder signal input. (Pulse ratio 1 : 1 )		5V DC line driver output (RS-422 compliance)	
	Power supply for encoder	EP5	+5V DC power supply	EG	Total supply capacity of EP5 and EP12 (250 mA max.)	
		EP12	+12V DC power supply			
Functional Grounding terminal FG		FG	Connect to the Functional Grounding connection. (Screw size: M3)			

**Installation**Install the unit in SLOT2 and tighten with screws.



## **Ordering Information**

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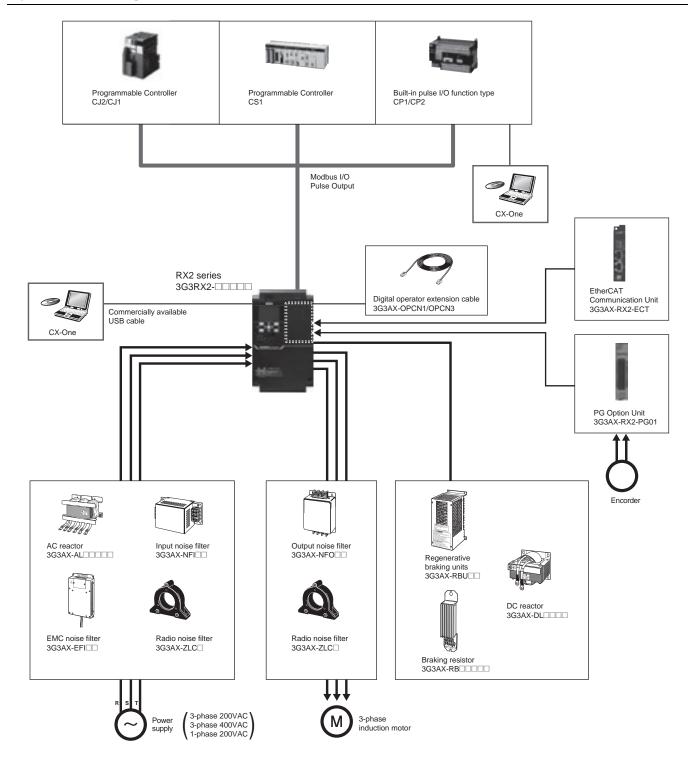
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# **System Configuration**



# **High-function General-purpose Inverters RX2 Series Interpreting Model Numbers**

# 3G3RX2-A2055

Max.	Applicable Motor Capacity Standard	Rating (ND)
004	0.4 kW	
007	0.75 kW	
015	1.5 kW	
022	2.2 kW	
037	3.7 kW	
055	5.5 kW	
075	7.5 kW	
110	11 kW	
150	15 kW	
185	18.5 kW	
220	22 kW	
300	30 kW	
370	37 kW	
450	45 kW	
550	55 kW	
750	75 kW	
900	90 kW	
11k	110 kW	
13k	132 kW	
, , , , , , , , , , , , , , , , , , ,		
Volta	ge class	
2	3-phase 200 VAC (200-V class)	
4	3-phase 400 VAC (400-V class)	
Enclo	osure rating	
А	IP20/UL open type	

IP00/UL open type

# **Ordering Information**

## **RX2 series Inverter Models**

		Max. applicabl	e motor capacity		
Rated voltage	Enclosure ratings	Normal Duty (ND)	Low Duty (LD)/ Very Low Duty (VLD)	Model	
		0.4 kW	0.75 kW	3G3RX2-A2004	
		0.75 kW	1.5 kW	3G3RX2-A2007	
		1.5 kW	2.2 kW	3G3RX2-A2015	
		2.2 kW	3.7 kW	3G3RX2-A2022	
		3.7 kW	5.5 kW	3G3RX2-A2037	
		5.5 kW	7.5 kW	3G3RX2-A2055	
		7.5 kW	11 kW	3G3RX2-A2075	
3-phase 200 VAC	IP20	11 kW	15 kW	3G3RX2-A2110	
		15 kW	18.5 kW	3G3RX2-A2150	
		18.5 kW	22 kW	3G3RX2-A2185	
		22 kW	30 kW	3G3RX2-A2220	
		30 kW	37 kW	3G3RX2-A2300	
		37 kW	45 kW	3G3RX2-A2370	
		45 kW	55 kW	3G3RX2-A2450	
		55 kW	75 kW	3G3RX2-A2550	
		0.75 kW	1.5 kW	3G3RX2-A4007	
		1.5 kW	2.2 kW	3G3RX2-A4015	
		2.2 kW	3.7 kW	3G3RX2-A4022	
		3.7 kW	5.5 kW	3G3RX2-A4037	
		5.5 kW	7.5 kW	3G3RX2-A4055	
		7.5 kW	11 kW	3G3RX2-A4075	
	IP20	11 kW	15 kW	3G3RX2-A4110	
	IP20	15 kW	18.5 kW	3G3RX2-A4150	
3-phase 400 VAC		18.5 kW	22 kW	3G3RX2-A4185	
3-phase 400 VAC		22 kW	30 kW	3G3RX2-A4220	
		30 kW	37 kW	3G3RX2-A4300	
		37 kW	45 kW	3G3RX2-A4370	
		45 kW	55 kW	3G3RX2-A4450	
		55 kW	75 kW	3G3RX2-A4550	
		75 kW	90 kW	3G3RX2-B4750	
	IP00	90 kW	110 kW	3G3RX2-B4900	
	IPUU	110 kW	132 kW	3G3RX2-B411K	
		132 kW	160 kW	3G3RX2-B413K	

## **Communication Unit**

Name	Model
EtherCAT Communication Unit	3G3AX-RX2-ECT

# **Related Options**

Name		Specifications	Model
		General purpose with Braking resistor	3G3AX-RBU21
	3-phase 200 VAC	High Regeneration purpose with Braking resistor	3G3AX-RBU22
	3-priase 200 VAC	General purpose for 30 kW *	3G3AX-RBU23
Regenerative Braking Units		General purpose for 55 kW *	3G3AX-RBU24
		General purpose with Braking resistor	3G3AX-RBU41
	3-phase 400 VAC	General purpose for 30 kW *	3G3AX-RBU42
		General purpose for 55 kW *	3G3AX-RBU43
		Resistor 120 W, 180 $\Omega$	3G3AX-RBA1201
	Compact type	Resistor 120 W, 100 $\Omega$	3G3AX-RBA1202
	Compact type	Resistor 120 W, 50 $\Omega$	3G3AX-RBA1203
		Resistor 120 W, 35 $\Omega$	3G3AX-RBA1204
		Resistor 200 W, 180 $\Omega$	3G3AX-RBB2001
Braking Resistor	Ctan dard tune	Resistor 200 W, 100 $\Omega$	3G3AX-RBB2002
	Standard type	Resistor 300 W, 50 $\Omega$	3G3AX-RBB3001
		Resistor 400 W, 35 Ω	3G3AX-RBB4001
		Resistor 400 W, 50 $\Omega$	3G3AX-RBC4001
	Medium capacity type	Resistor 600 W, 35 $\Omega$	3G3AX-RBC6001
		Resistor 1200 W, 17 Ω	3G3AX-RBC12001

<sup>\*</sup> The braking resistor is optionally required.

#### **Regenerative Braking Unit and Braking Resistor Combination**

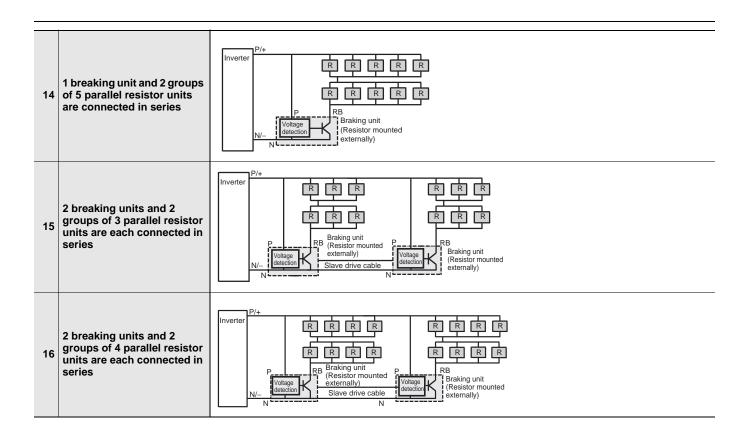
Select the combination of the regenerative braking unit(s) and the braking resistor(s) as follows, according to your inverter. If the usage rate exceeds 10% ED, or if you need a torque larger than the approximate braking torque, you need to follow the instruction provided in Braking Resistor Selection

- Inverter: Select the model of your inverter. The table below assumes that your inverter is used in the heavy load mode and connected to a single
  motor with the same capacity. Make sure that the approximate braking torque in the table shows the assumed value per a motor with
  the same capacity at ND mode. When using this inverter at LD or VLD mode, you need to calculate the torque value by dividing VLD
  by ND.
- Operating conditions: Show the torque during deceleration and the deceleration time (in % ED) calculated as a percentage of the cycle time for 1 cycle of operation including the stop time.
- Braking unit/Breaking resistor: Show the required the model and number of units.
- Connection form: Show the configuration of the regenerative braking unit(s) and braking resistor(s) illustrated in the connection form table below.
- Restrictions: Show the maximum deceleration time allowable for the combination shown here and the minimum resistance that can be connected to the inverter's built-in regenerative braking circuit or external regenerative braking unit(s).

	Inve	rter	Operatir	ng conditions	Braking u	nit	Braking resis	tor		Restr	ictions
Voltage class	Max. applicable motor capacity (kW)	Model	%ED (%)	Approximate braking torque (%)	Model	Number of units	Model	Number of units	Connec- tion form	Allowable continuous braking time(s)	Min. connectable resistance (Ω)
	0.4	3G3RX2-A2004	3.0%	220%	Built-in Inverter		3G3AX-RBA1201	1	1	20	50
	0.4	3G3RAZ-A2004	10.0%	220%	Built-in inverter		3G3AX-RBB2001	1	1	30	50
	0.75	3G3RX2-A2007	3.0%	120%	Built-in Inverter		3G3AX-RBA1201	1	1	20	50
	0.75	3G3RAZ-A2007	10.0%	120%	Built-in inverter		3G3AX-RBB2001	1	1	30	50
	1.5	3G3RX2-A2015	2.5%	110%	Built-in Inverter		3G3AX-RBA1202	1	1	12	35
	1.5	3G3RAZ-AZ015	10.0%	215%	Built-in inverter		3G3AX-RBC4001	1	1	10	35
	2.2	3G3RX2-A2022	3.0%	150%	Built-in Inverter		3G3AX-RBB3001	1	1	30	35
	2.2	3G3KX2-A2022	10.0%	150%	Built-iii iiiveitei		3G3AX-RBC4001	1	1	10	35
	3.7	3G3RX2-A2037	3.0%	125%	Built-in Inverter		3G3AX-RBB4001	1	1	20	35
	3.7	3G3RAZ-A2U31	10.0%	125%	Built-in inverter		3G3AX-RBC6001	1	1	10	35
	5.5	3G3RX2-A2055	3.0%	120%	Built-in Inverter		3G3AX-RBB3001	2	2	30	16
	5.5	5.5 3G3RAZ-AZU55	10.0%	120%	Built-in inverter		3G3AX-RBC4001	2	2	10	16
	7.5	3G3RX2-A2075	3.0%	125%	Built-in Inverter		3G3AX-RBB4001	2	2	20	10
	7.5	3G3RAZ-AZ075	10.0%	125%	Built-in inverter		3G3AX-RBC6001	2	2	10	10
200-V	11	3G3RX2-A2110	3.0%	125%	Built-in Inverter		3G3AX-RBB4001	3	4	20	10
Class	''	3G3RAZ-AZ110	10.0%	125%	Built-in inverter		3G3AX-RBC6001	3	4	10	10
	15	3G3RX2-A2150	3.0%	130%	Built-in Inverter		3G3AX-RBC12001	2	2	10	7.5
	15	3G3RAZ-AZ130	10.0%	130%	Built-in inverter		3G3AX-RBC12001	2	2	10	7.5
	18.5	3G3RX2-A2185	3.0%	105%	Built-in Inverter		3G3AX-RBC12001	2	2	10	7.5
	10.5	3G3RAZ-AZ103	10.0%	105%	Built-iii iiivertei		3G3AX-RBC12001	2	2	10	7.5
	22	3G3RX2-A2220	3.0%	130%	Duilt in Investor		3G3AX-RBC12001	3	4	10	5
	22	3G3RAZ-AZZZU	10.0%	130%	Built-in Inverter		3G3AX-RBC12001	3	4	10	5
	30	3G3RX2-A2300	3.0%	160%	3G3AX-RBU24	1	3G3AX-RBC12001	5	11	10	2
	30	3G3RAZ-AZ300	10.0%	160%	3G3AX-RBU24	1	3G3AX-RBC12001	5	11	10	2
	37	3G3RX2-A2370	3.0%	130%	3G3AX-RBU24	1	3G3AX-RBC12001	5	11	10	2
	31	3G3KX2-A2370	10.0%	130%	3G3AX-RBU24	1	3G3AX-RBC12001	5	11	10	2
	45	3G3RX2-A2450	3.0%	130%	3G3AX-RBU24	1	3G3AX-RBC12001	6	12	10	2
	45	3G3KAZ-AZ43U	10.0%	130%	3G3AX-RBU24	1	3G3AX-RBC12001	6	12	10	2
	55	3G3RX2-A2550	3.0%	120%	3G3AX-RBU24	1	3G3AX-RBC12001	7	13	10	2
	33	303NAZ-A2330	10.0%	120%	3G3AX-RBU24	1	3G3AX-RBC12001	7	13	10	2

	Inve	rter	Operation	ng conditions	Braking ι	ınit	Braking resis	stor		Restr	ictions
Voltage class	Max. applicable motor capacity (kW)	Model	%ED (%)	Approximate braking torque (%)	Model	Number of units	Model	Number of units	Connection form	Allowable continuous braking time(s)	Min. connectable resistance (Ω)
	0.75	2C2DV2 A4007	3.0%	220%	Duilt in Investor		3G3AX-RBA1201	2	3	20	100
	0.75	3G3RX2-A4007	10.0%	220%	Built-in Inverter		3G3AX-RBB2001	2	3	30	100
	4.5	2C2DV2 A4045	3.0%	120%	Duilt in Investor		3G3AX-RBA1201	2	3	20	100
	1.5	3G3RX2-A4015	10.0%	120%	Built-in inverter		3G3AX-RBB2001	2	3	30	100
	2.2	2C2DV2 A4022	%ED (%)         braking torque (%)         Model         Number of units         Model         Number of units         tion form of units           3.0%         220%         Built-in Inverter         3G3AX-RBA1201         2         3           3.0%         120%         Built-in Inverter         3G3AX-RBA1201         2         3           10.0%         120%         Built-in Inverter         3G3AX-RBA1201         2         3           2.5%         150%         Built-in Inverter         3G3AX-RBA2001         2         3           10.0%         175%         Built-in Inverter         3G3AX-RBC4001         2         3           3.0%         120%         Built-in Inverter         3G3AX-RBA3001         2         3           10.0%         125%         Built-in Inverter         3G3AX-RBC4001         2         3           3.0%         125%         Built-in Inverter         3G3AX-RBB3001         2         3           3.0%         120%         Built-in Inverter         3G3AX-RBC4001         2         3           3.0%         120%         Built-in Inverter         3G3AX-RBC4001         4         5           3.0%         120%         Built-in Inverter	12	100						
	2.2	3G3RX2-A4022	10.0%	220%	Built-in inverter		3G3AX-RBC4001	2	3	10	100
	0.7	0000000 44007	3.0%	175%	Built-in Inverter  Built-in Inverter	30	70				
	3.7	3G3RX2-A4037	10.0%	175%	Built-in Inverter		3G3AX-RBC4001	2	3	10	70
		0000000 44055	3.0%	120%	D 11: 1		Model   Number of units   Connetion follows   Signature   Signat	3	30	70	
	5.5	3G3RX2-A4055	10.0%	120%	Built-in Inverter		3G3AX-RBC4001	2	3	10	70
		3G3RX2-A4075	3.0%	125%	B 11: 1		3G3AX-RBB4001	2	3	20	35
7.5	3G3RX2-A4075	10.0%	125%	Built-in Inverter		3G3AX-RBC6001	2	3	10	35	
	4.4	0000000 44440	3.0%	120%	D 11: 1		3G3AX-RBB3001	4	5	30	35
	15	3G3RX2-A4110	10.0%	120%	Built-in Inverter		3G3AX-RBC4001	4	5	10	35
		202DV2 A4450	3.0%	125%	Duilt in Income		3G3AX-RBB4001	4	5	20	24
		3G3RX2-A4150	10.0%	125%	Built-in inverter		3G3AX-RBC6001	4	5	10	24
		3G3RX2-A4185	3.0%	140%	Duilt in Investor		3G3AX-RBB3001	8	6	30	24
400-V	18.5		10.0%	140%	Built-in inverter		3G3AX-RBC4001	8	6	10	24
Class	00	202DV2 A 4000	3.0%	120%	5		3G3AX-RBB3001	8	6	30	20
	22	3G3RX2-A4220	10.0%	120%	Built-in inverter		3G3AX-RBC4001	8	6	10	20
	20	2C2DV2 A4200	10.0%	100%	Built-in Inverter		3G3AX-RBC12001	4	5	10	15
	30	3G3RX2-A4300	10.0%	150%	3G3AX-RBU42	1	3G3AX-RBC12001	6	9	10	10
	27	2C2DV2 A4270	3.0%	100%	Built-in Inverter		3G3AX-RBC12001	4	5	10	15
	37	3G3RX2-A4370	10.0%	155%	3G3AX-RBU43	1	3G3AX-RBC12001	6	9	10	6
	45	202DV2 A4450	3.0%	130%	3G3AX-RBU43	1	3G3AX-RBC12001	6	9	10	6
	45	3G3RX2-A4450	10.0%	130%	3G3AX-RBU43	1	3G3AX-RBC12001	6	9	10	6
	55	3G3RX2-A4550	3.0%	140%	3G3AX-RBU43	1	3G3AX-RBC12001	8	10	10	6
	55	3G3RAZ-A4550	10.0%	140%	3G3AX-RBU43	1	3G3AX-RBC12001	8	10	10	6
	75	2C2DV2 D4750	3.0%	130%	3G3AX-RBU43	1	3G3AX-RBC12001	10	14	10	6
	/5	3G3RX2-B4750	10.0%	130%	3G3AX-RBU43	1	3G3AX-RBC12001	10	14	10	6
	00	2C2DV2 D4000	3.0%	105%	3G3AX-RBU43	1	3G3AX-RBC12001	10	14	10	6
	90	3G3RX2-B4900	10.0%	105%	3G3AX-RBU43	1	3G3AX-RBC12001	10	14	10	6
	110	2C2DV2 D4441/	3.0%	105%	3G3AX-RBU43	2	3G3AX-RBC12001	12	15	10	6
	110	3G3RX2-B411K	10.0%	105%	3G3AX-RBU43	2	3G3AX-RBC12001	12	15	10	6
	132	3G3RX2-B413K	3.0%	115%	3G3AX-RBU43	2	3G3AX-RBC12001	16	16	10	6
	132	303RAZ-D413K	10.0%	115%	3G3AX-RBU43	2	3G3AX-RBC12001	16	16	10	6

#### **Connection configuration TYPE TYPE** Inverter Inverter 1 breaking unit 1 resistor unit R Resisto and 3 resistor units connected (Resistor in parallel 2 resistor units externally) 2 connected in parallel Inverter 1 breaking unit and 2 groups of 2 Inverte 2 resistor units parallel resistor connected in units are series connected in series 3 resistor units connected in parallel Inverter 1 breaking unit and 2 groups of 3 parallel resistor Inverter 2 groups of 2 units are parallel resistor connected in units are series connected in series Inverter Inverter 2 groups of 4 1 breaking unit parallel resistor and 2 groups of 4 units are parallel resistor connected in units connected series are connected in Braking unit series (Resistor mounted externally) 1 breaking unit and 5 11 resistor units connected in Braking unit (Resistor mounted parallel externally) Inverter R 1 breaking unit and 6 12 resistor units connected in RB Braking unit parallel (Resistor mounted externally) Inverte R R R R R 1 breaking unit and 7 13 resistor unitsconnected in parallel (Resistor mounted externally)



Name	Model
Radio Noise Filter	3G3AX-ZCL2
Radio Noise Filler	3G3AX-ZCL1

		Inverter								
Name	Voltage class	Max. applicable motor capacity [kW]	Model	Load specification selection	Max. applicable motor capacity [kW]	Rated input current [A]	Model			
				ND	0.4	3.3	202 AV NEI24			
		0.4	3G3RX2-A2004	LD	0.75	3.9				
				VLD	0.75	3.9	3G3AX-NFI21			
				ND	0.75	5.5				
		0.75	3G3RX2-A2007	LD	1.5	7.2				
				VLD	1.5	7.2	3G3AX-NFI22			
				ND	1.5	8.3				
		1.5	3G3RX2-A2015	LD	2.2	10.8				
				VLD	2.2	10.8				
				ND	2.2	12	_			
		2.2	3G3RX2-A2022	LD	3.7	13.9	3G3AX-NFI23			
		VLD	VLD	3.7	13.9	1				
				ND	3.7	18	1			
		3.7	3G3RX2-A2037	LD	5.5	23				
				VLD	5.5	23	3G3AX-NFI24			
			ND	5.5	26					
		5.5	3G3RX2-A2055	LD	7.5	37	3G3AX-NFI25			
				VLD	7.5	37				
			ND	7.5	35	-				
		7.5	3G3RX2-A2075	LD	11	48				
			0001012712070	VLD	11	48	3G3AX-NFI26			
				ND	11	51	-			
put Noise	200-V		3G3RX2-A2110	LD	15	64	3G3AX-NFI27 3G3AX-NFI28			
lter	class		3G3RX2-A2150	VLD	15	64				
				ND	15	70				
		15		LD	18.5	80				
		10		VLD	18.5	80				
				ND	18.5	84				
		18.5	3G3RX2-A2185	LD	22	94				
		10.5	3031(XZ-AZ 103	VLD	22	94				
				ND	22	105				
		22	3G3RX2-A2220	LD	30	120	3G3AX-NFI29			
		22	3G3RA2-A2220	VLD						
					30	120	_			
		20	202DV0 40200	ND	30	133				
		30	3G3RX2-A2300	LD	37	150	20247 11510			
				VLD	37	150	3G3AX-NFI2A			
		07	000DVC 40070	ND	37	160				
		37	3G3RX2-A2370	LD	45	186	20047 ::=:=			
				VLD	45	186	3G3AX-NFI2B			
			000000	ND	45	200				
		45	3G3RX2-A2450	LD	55	240				
				VLD	55	240	3G3AX-NFI2C			
				ND	55	242				
		55	3G3RX2-A2550	LD	75	280				
				VLD	75	280				

		Inverter								
Name	Voltage class	Max. applicable motor capacity [kW]	Model	Load specification selection	Max. applicable motor capacity [kW]	Rated input current [A]	Model			
				ND	0.75	2.8				
		0.75	3G3RX2-A4007	LD	1.5	4.3				
				VLD	1.5	4.3				
			3G3RX2-A4015	ND	1.5	4.2	3G3AX-NFI41			
		1.5		LD	2.2	5.9				
				VLD	2.2	5.9				
				ND	2.2	5.8				
		2.2	3G3RX2-A4022	LD	3.7	8.1				
						VLD	3.7	8.1	3G3AX-NFI42	
				ND	3.7	9.8				
		3.7 3G3RX2-A4037	3G3RX2-A4037	LD	5.5	13.3				
			VLD	VLD	5.5	13.3				
		3G3RX2-A4055	ND	5.5	15	20247 115115				
	5.5		LD	7.5	20	3G3AX-NFI43				
			VLD	7.5	20					
			ND	7.5	21					
		7.5	3G3RX2-A4075	LD	11	24	3G3AX-NFI44			
				VLD	11	24				
				ND	11	28	3G3AX-NFI45			
		11 400-V class	3G3RX2-A4110	LD	15	32				
nput Noise	400-\/			VLD	15	32				
ilter	class			ND	15	35				
		15	3G3RX2-A4150	LD	18.5	41				
				VLD	18.5	41	3G3AX-NFI46 3G3AX-NFI47			
				ND	18.5	42				
		18.5	3G3RX2-A4185	LD	22	47				
				VLD	22	47				
				ND	22	53	1			
		22	3G3RX2-A4220	LD	30	63				
				VLD	30	63	3G3AX-NFI48			
				ND	30	64	1			
		30	3G3RX2-A4300	LD	37	77				
				VLD	37	77	3G3AX-NFI49			
				ND	37	83	1			
		37	3G3RX2-A4370	LD	45	94				
			VLD	45	94	-				
				ND	45	100	1			
		45	3G3RX2-A4450	LD	55	116	3G3AX-NFI4A			
		-		VLD	55	116	-			
				ND	55	121	1			
		55	3G3RX2-A4550	LD	75	149				
		55	3G3RX2-A4550		-	1				

				Inverter				
Name	Voltage class	Max. applicable motor capacity [kW]	Model	Load specification selection	Max. applicable motor capacity [kW]	Rated input current [A]	Model	
				ND	0.4	3.3		
		0.4	3G3RX2-A2004	LD	0.75	3.9	20247 55144	
				VLD	0.75	3.9	3G3AX-EFI41	
				ND	0.75	5.5		
		0.75	3G3RX2-A2007	LD	1.5	7.2		
				VLD	1.5	7.2	3G3AX-EFI42	
				ND	1.5	8.3		
		1.5	3G3RX2-A2015	LD	2.2	10.8		
				VLD	2.2	10.8		
				ND	2.2	12	†	
		2.2	3G3RX2-A2022	LD	3.7	13.9	3G3AX-EFI43	
				VLD	3.7	13.9		
				ND	3.7	18		
		3.7	3G3RX2-A2037	LD	5.5	23		
				VLD	5.5	23	3G3AX-EFI44	
	-			ND	5.5	26		
		5.5	3G3RX2-A2055	LD	7.5	37		
				VLD	7.5	37	3G3AX-EFI45	
				ND	7.5	35	1	
MC Noise	200-V	7.5	3G3RX2-A2075	LD	11	48		
ilter *	ciass	class	3G3RX2-A2110	VLD	11	48	3G3AX-EFI47	
				ND	11	51	1	
		11		LD	15	64		
				VLD	15	64	3G3AX-EFI48	
				ND	15	70	1	
		15	3G3RX2-A2150	LD	18.5	80		
				VLD	18.5	80	3G3AX-EFI49	
				ND	18.5	84	1	
		18.5	3G3RX2-A2185	LD	22	94		
				VLD	22	94		
				ND	22	105		
		22	3G3RX2-A2220	LD	30	120	3G3AX-EFI4A	
				VLD	30	120	1	
			1	ND	30	133	1	
		30	3G3RX2-A2300	LD	37	150		
			200.0.27.2000	VLD	37	150	3G3AX-EFI4B	
				ND	37	160		
		37	3G3RX2-A2370	LD	45	186		
		31	3301772-772010					
				VLD	45	186		

<sup>\*</sup> Although an EMC Noise Filter is built into the RX2, it may be necessary to provide another EMC Noise Filter when the cable between the Motor and the Inverter is long.

		Inverter									
Name	Voltage class	Max. applicable motor capacity [kW]	Model	Load specification selection	Max. applicable motor capacity [kW]	Rated input current [A]	Model				
				ND	0.75	2.8					
		0.75	3G3RX2-A4007	LD	1.5	4.3					
				VLD	1.5	4.3					
				ND	1.5	4.2	3G3AX-EFI41				
		1.5	3G3RX2-A4015	LD	2.2	5.9					
				VLD	2.2	5.9					
			ND	2.2	5.8						
		2.2	3G3RX2-A4022	LD	3.7	8.1					
				VLD	3.7	8.1	3G3AX-EFI42				
				ND	3.7	9.8					
		3.7	3G3RX2-A4037	LD	5.5	13.3					
				VLD	5.5	13.3					
				ND	5.5	15	20247 557				
		5.5	3G3RX2-A4055	LD	7.5	20	3G3AX-EFI43				
				VLD	7.5	20	1				
				ND	7.5	21					
		7.5	3G3RX2-A4075	LD	11	24	3G3AX-EFI44				
				VLD	11	24					
			ND	11	28						
		11	3G3RX2-A4110	LD	15	32	3G3AX-EFI45				
				VLD	15	32					
				ND	15	35					
		15	3G3RX2-A4150	LD	18.5	41					
IC Noise	400-V	,	3G3RX2-A4185	VLD	18.5	41	3G3AX-EFI46 3G3AX-EFI47 3G3AX-EFI48				
ter *	class			ND	18.5	42					
		18.5		LD	22	47					
		.0.0		VLD	22	47					
			3G3RX2-A4220	ND	22	53					
		22		LD	30	63					
				VLD	30	63					
				ND	30	64					
		30	3G3RX2-A4300	LD	37	77					
		30	00010/12 /14000	VLD	37	77	3G3AX-EFI49				
				ND	37	83					
		37	3G3RX2-A4370	LD	45	94					
		<i>51</i>	55517/2 /14570	VLD	45	94	-				
				ND	45	100	-				
		45	3G3RX2-A4450	LD	55	116	3G3AX-EFI4A				
		75	30311/12-74430	VLD	55	116	-				
				ND	55	121	-				
		55	3G3RX2-A4550	LD	75	149					
		ວວ	3G3NAZ-A433U				4				
				VLD	75 75	149	4				
		75	202DV2 D 4752	ND	75	164	3G3AX-EFI4B				
		75	3G3RX2-B4750	LD	90	176	-				
				VLD	90	176					
		65	000000000000000000000000000000000000000	ND	90	194					
	90	3G3RX2-B4900	LD	110	199						

<sup>\*</sup> Although an EMC Noise Filter is built into the RX2, it may be necessary to provide another EMC Noise Filter when the cable between the Motor and the Inverter is long.

	_			Inverter				
Name	Voltage class	Max. applicable motor capacity [kW]	Model	Load specification selection	Max. applicable motor capacity [kW]	Rated input current [A]	Model	
				ND	0.4	3		
		0.4	3G3RX2-A2004	LD	0.75	3.7	3G3AX-NFO01	
				VLD	0.75	3.7	3G3AX-NFOUT	
				ND	0.75	5		
		0.75	3G3RX2-A2007	LD	1.5	6.3		
				VLD	1.5	6.3		
				ND	1.5	7.5	2024Y NEO02	
			1.5	3G3RX2-A2015	LD	2.2	9.4	3G3AX-NFO02
						VLD	2.2	9.4
				ND	2.2	10.5		
		2.2	3G3RX2-A2022	LD	3.7	12		
				VLD	3.7	12		
				ND	3.7	16.5		
	3.7	3G3RX2-A2037	LD	5.5	19.6	3G3AX-NFO03		
				VLD	5.5	19.6		
				ND	5.5	24		
		5.5	3G3RX2-A2055	LD	7.5	30		
				VLD	7.5	30	-	
			3G3RX2-A2075	ND	7.5	32	3G3AX-NFO04	
Output Noise	200-V	7.5		LD	11	44		
ilter	class			VLD	11	44		
				ND	11	46		
		11	3G3RX2-A2110	LD	15	58		
				VLD	15	58	3G3AX-NFO05	
				ND	15	64	-	
		15	3G3RX2-A2150	LD	18.5	73		
				VLD	18.5	73	-	
				ND	18.5	76	-	
		18.5	3G3RX2-A2185	LD	22	85	3G3AX-NFO06	
				VLD	22	85		
				ND	22	95		
		22	3G3RX2-A2220	LD	30	113		
				VLD	30	113	-	
				ND	30	121	-	
		30	3G3RX2-A2300	LD	37	140	3G3AX-NFO07	
		30		VLD	37	140		
				ND	37	145		
		37	3G3RX2-A2370	LD	45	169		
		37		VLD	45	169		

				Inverter			
Name	Voltage class	Max. applicable motor capacity [kW]	Model	Load specification selection	Max. applicable motor capacity [kW]	Rated input current [A]	Model
				ND	0.75	2.5	
		0.75	3G3RX2-A4007	LD	1.5	3.1	
				VLD	1.5	3.1	-
				ND	1.5	3.8	3G3AX-NFO01
		1.5	3G3RX2-A4015	LD	2.2	4.8	-
				VLD	2.2	4.8	-
				ND	2.2	5.3	-
		2.2	3G3RX2-A4022	LD	3.7	6.7	
				VLD	3.7	6.7	3G3AX-NFO02
				ND	3.7	9	-
		3.7	3G3RX2-A4037	LD	5.5	11.1	
				VLD	5.5	11.1	-
				ND	5.5	14	1
		5.5	3G3RX2-A4055	LD	7.5	16	1
				VLD	7.5	16	3G3AX-NFO03
		7.5		ND	7.5	19	
			3G3RX2-A4075	LD	11	22	
			VLD	11	22	1	
			ND	11	25		
		11	3G3RX2-A4110	LD	15	29	
			VLD	15	29		
			ND	15	32		
Output Noise			3G3RX2-A4150	LD	18.5	37	-
ilter	class		VLD	18.5	37	3G3AX-NFO04	
				ND	18.5	38	
		18.5	3G3RX2-A4185	LD	22	43	
				VLD	22	43	
				ND	22	48	
		22 3G3RX2-A	3G3RX2-A4220	LD	30	57	
				VLD	30	57	-
				ND	30	58	
		30	3G3RX2-A4300	LD	37	70	3G3AX-NFO05
				VLD	37	70	
				ND	37	75	
		37	3G3RX2-A4370	LD	45	85	
				VLD	45	85	3G3AX-NFO06
			ND	45	91	1	
	45	3G3RX2-A4450	LD	55	105		
	-		VLD	55	105	-	
				ND	55	112	-
		55	3G3RX2-A4550	LD	75	135	3G3AX-NFO07
				VLD	75	135	-
				ND	75	149	-
		75	3G3RX2-B4750	LD	90	160	
			200.00	VLD	90	160	

				Inverter					
Name	Voltage class	Max. applicable motor capacity [kW]	Model	Load specification selection	Max. applicable motor capacity [kW]	Rated input current [A]	Model		
				ND	0.4	3.3	3G3AX-DL2004		
		0.4	3G3RX2-A2004	LD	0.75	3.9			
				VLD	0.75	3.9	3G3AX-DL2007		
				ND	0.75	5.5			
		0.75	3G3RX2-A2007	LD	1.5	7.2			
				VLD	1.5	7.2	3G3AX-DL2015		
				ND	1.5	8.3			
		1.5	3G3RX2-A2015	LD	2.2	10.8			
				VLD	2.2	10.8	3G3AX-DL2022		
				ND	2.2	12			
		2.2	3G3RX2-A2022	LD	3.7	13.9			
				VLD	3.7	13.9	3G3AX-DL2037		
				ND	3.7	18			
		3.7	3G3RX2-A2037	LD	5.5	23			
				VLD	5.5	23	3G3AX-DL2055		
			5.5 3G		ND	5.5	26	- 300AA-DL203	
		5.5		5.5 3G3RX2-	3G3RX2-A2055	LD	7.5	37	
				VLD	7.5	37	3G3AX-DL2075		
		7.5	3G3RX2-A2075	ND	7.5	35	-		
				LD	11	48			
	200-V	_		VLD	11	48	3G3AX-DL2110		
			11 3G3RX2-A2110	ND	11	51	_		
C Reactor		11		LD	15	64	3G3AX-DL2150		
	class			VLD	15	64			
		15		ND	15	70			
			15	15	15 3G3F	15 3G3RX2-A2150	LD	18.5	80
			0001012 712100	VLD	18.5	80	3G3AX-DL2220		
				ND	18.5	84			
		18.5	3G3RX2-A2185	LD	22	94			
		.0.0	0001012712100	VLD	22	94			
				ND	22	105			
		22	3G3RX2-A2220	LD	30	120			
		22	OGOTOKE NEEDO	VLD	30	120	3G3AX-DL2300		
				ND	30	133	-		
		30	3G3RX2-A2300	LD	37	150			
		30	30311/A2-7A2300	VLD	37	150	3G3AX-DL2370		
				ND	37	160	303AA-DL2370		
		37	3G3PY2 A2270	LD	45				
		31	3G3RX2-A2370	VLD	45	186 186	3G3AY-DI 24E0		
							3G3AX-DL2450		
		45	2C2DV2 42450	ND	45	200			
		45	3G3RX2-A2450	LD	55	240	2C2AV DI 2550		
				VLD	55	240	3G3AX-DL2550		
			000DVC 40550	ND	55	242			
		55	3G3RX2-A2550	LD	75	280			
				VLD	75	280			

Name	Voltage	Max. applicable			Inverter					
	class	motor capacity [kW]	Model	Load specification selection	Max. applicable motor capacity [kW]	Rated input current [A]	Model			
				ND	0.75	2.8	3G3AX-DL400			
		0.75	3G3RX2-A4007	LD	1.5	4.3				
				VLD	1.5	4.3	3G3AX-DL401			
	=			ND	1.5	4.2				
		1.5	3G3RX2-A4015	LD	2.2	5.9				
				VLD	2.2	5.9	3G3AX-DL402			
	-			ND	2.2	5.8				
		2.2	3G3RX2-A4022	LD	3.7	8.1				
				VLD	3.7	8.1	3G3AX-DL403			
	-			ND	3.7	9.8				
		3.7	3G3RX2-A4037	LD	5.5	13.3				
				VLD	5.5	13.3	3G3AX-DL405			
	-			ND	5.5	15				
		5.5	3G3RX2-A4055	LD	7.5	20	3G3AX-DL4075			
				VLD	7.5	20				
			3G3RX2-A4075	ND	7.5	21	3G3AX-DL4110			
		7.5		LD	11	24				
				VLD	11	24				
	400-V class		11 3G3RX2-A4110	ND	11	28	3G3AX-DL415			
		11		LD	15	32				
				VLD	15	32				
C Reactor				ND	15	35				
		15 3G3RX2-A4150	LD	18.5	41					
				VLD	18.5	41	-			
				ND	18.5	42				
		18.5	18.5 3G3RX2-A4185	LD	22	47	3G3AX-DL4220			
					VLD	22	47	-		
	-			ND	22	53				
		22	3G3RX2-A4220	LD	30	63				
				VLD	30	63	3G3AX-DL430			
				ND	30	64	1			
		30	3G3RX2-A4300	LD	37	77				
				VLD	37	77	3G3AX-DL437			
				ND	37	83	1			
		37	3G3RX2-A4370	LD	45	94				
				VLD	45	94	3G3AX-DL445			
				ND	45	100	1			
		45	3G3RX2-A4450	LD	55	116				
				VLD	55	116	3G3AX-DL455			
	-			ND	55	121	1			
		55	3G3RX2-A4550	LD	75	149				
		55 3	55 3G3RX2-A4550	<del></del>	-	· · ·				

				Inverter			
Name	Voltage class	Max. applicable motor capacity [kW]	Model	Load specification selection	Max. applicable motor capacity [kW]	Rated input current [A]	Model
				ND	0.4	3.3	
		0.4	3G3RX2-A2004	LD	0.75	3.9	
				VLD	0.75	3.9	
				ND	0.75	5.5	3G3AX-AL2025
		0.75	3G3RX2-A2007	LD	1.5	7.2	
				VLD	1.5	7.2	
				ND	1.5	8.3	
		1.5	3G3RX2-A2015	LD	2.2	10.8	
				VLD	2.2	10.8	
				ND	2.2	12	
		2.2	3G3RX2-A2022	LD	3.7	13.9	3G3AX-AL2055
				VLD	3.7	13.9	
				ND	3.7	18	-
		3.7	3G3RX2-A2037	LD	5.5	23	
				VLD	5.5	23	1
			3G3RX2-A2055	ND	5.5	26	- 3G3AX-AL2110
		5.5		LD	7.5	37	
				VLD	7.5	37	
				ND	7.5	35	-
		7.5	3G3RX2-A2075	LD	11	48	
	r 200-V class			VLD	11	48	
			3G3RX2-A2110	ND	11	51	- 3G3AX-AL2220
AC Reactor				LD	15	64	
10 Houdion				VLD	15	64	
			15 3G3RX2-A2150	ND	15	70	3G3AX-AL2330
		15		LD	18.5	80	
		10		VLD	18.5	80	
				ND	18.5	84	
		18.5	3G3RX2-A2185	LD	22	94	
		10.5	3031(A2-A2103	VLD	22	94	
				ND	22	105	
		22	3G3RX2-A2220	LD	30	120	
		22	3G3KA2-A2220	VLD	30	120	-
				ND	30	133	_
		20	3G3RX2-A2300				3G3AX-AL2500
		30	3G3KAZ-AZ3UU	LD	37	150	-
				VLD	37	150	
		07	202DV2 40270	ND	37	160	
		37	3G3RX2-A2370	LD	45	186	-
				VLD	45	186	-
		45	0000000 45 155	ND	45	200	3G3AX-AL2750
		45	3G3RX2-A2450	LD	55	240	-
				VLD	55	240	
			000000	ND	55	242	
		55	3G3RX2-A2550	LD	75	280	
				VLD	75	280	

				Inverter			
Name	Voltage class	Max. applicable motor capacity [kW]	Model	Load specification selection	Max. applicable motor capacity [kW]	Rated input current [A]	Model
				ND	0.75	2.8	
		0.75	3G3RX2-A4007	LD	1.5	4.3	
				VLD	1.5	4.3	3G3AX-AL402
				ND	1.5	4.2	
		1.5	3G3RX2-A4015	LD	2.2	5.9	
				VLD	2.2	5.9	
				ND	2.2	5.8	†
		2.2	3G3RX2-A4022	LD	3.7	8.1	3G3AX-AL405
				VLD	3.7	8.1	
				ND	3.7	9.8	
		3.7	3G3RX2-A4037	LD	5.5	13.3	
				VLD	5.5	13.3	1
				ND	5.5	15	1
		5.5	3G3RX2-A4055 3G3RX2-A4075	LD	7.5	20	3G3AX-AL4110 3G3AX-AL4220 3G3AX-AL4230
		7.5		VLD	7.5	20	
				ND	7.5	21	
				LD	11	24	
				VLD	11	24	
			3G3RX2-A4110	ND	11	28	
		400-V class 15		LD	15	32	
	400-\/			VLD	15	32	
AC Reactor			3G3RX2-A4150	ND	15	35	
				LD	18.5	41	
				VLD	18.5	41	
			3G3RX2-A4185	ND	18.5	42	
		18.5		LD	22	47	
				VLD	22	47	
				ND	22	53	
		22	3G3RX2-A4220	LD	30	63	
				VLD	30	63	+
				ND	30	64	
		30	3G3RX2-A4300	LD	37	77	3G3AX-AL450
				VLD	37	77	
				ND	37	83	
		37	3G3RX2-A4370	LD	45	94	
			VLD	45	94	†	
				ND	45	100	†
		45	3G3RX2-A4450	LD	55	116	3G3AX-AL4750
				VLD	55	116	†
				ND	55	121	1
		55					
		55	3G3RX2-A4550	LD	75	149	

,		
Name	Specifications	Model
PG Option Unit	For Position or Frequency Control	3G3AX-RX2-PG01
Digital Operator Connecting	RJ45 connector, EIA568-compliant cable (UTP category 5), Cable Length 1 m	3G3AX-OPCN1
Cable	RJ45 connector, EIA568-compliant cable (UTP category 5), Cable Length 3 m	3G3AX-OPCN3

#### **Recommended EtherCAT Communications Cables**

Use a straight STP (shielded twisted-pair) cable of category 5 or higher with double shielding (aluminum tape and braiding) for EtherCAT.

#### **Cable with Connectors**

	Item	Recommended manufacturer	Cable length (m)	Model
	Cable with Connectors on Both Ends (B.145/B.145)		0.3	XS6W-6LSZH8SS30CM-Y
	Cable with Connectors on Both Ends (RJ45/RJ45) Standard RJ45 plugs *2		0.5	XS6W-6LSZH8SS50CM-Y
Wire gauge and number of pairs: AWG26, 4-pair cable	Cable color: Yellow *3	OMRON	1	XS6W-6LSZH8SS100CM-Y
Cable sheath material: LSZH *1		OWRON	2	XS6W-6LSZH8SS200CM-Y
	- 4		3	XS6W-6LSZH8SS300CM-Y
			5	XS6W-6LSZH8SS500CM-Y
	Cable with Connectors on Both Ends (RJ45/RJ45) Rugged RJ45 plugs *2 Cable color: Light blue		0.3	XS5W-T421-AMD-K
		OMRON	0.5	XS5W-T421-BMD-K
			1	XS5W-T421-CMD-K
			2	XS5W-T421-DMD-K
			5	XS5W-T421-GMD-K
Wire gauge and number of pairs:			10	XS5W-T421-JMD-K
AWG22, 2-pair cable	Cable with Connectors on Both Ends		0.5	XS5W-T421-BMC-SS
	(M12 Straight/RJ45) Shield strengthening connector cable *4		1	XS5W-T421-CMC-SS
	M12/Smartclick connector and rugged RJ45 plug	OMBON	2	XS5W-T421-DMC-SS
	Cable color: Black	OMRON	3	XS5W-T421-EMC-SS
			5	XS5W-T421-GMC-SS
	-0		10	XS5W-T421-JMC-SS

- **\*1.** The lineup features Low Smoke Zero Halogen cables for in-cabinet use and PUR cables for out-of-cabinet use. Although the LSZH cable is single shielded, its communications and noise characteristics meet the standards.
- \*2. Cables with standard RJ45 plugs are available in the following lengths: 0.2 m, 0.3 m, 0.5 m, 1 m, 1.5 m, 2 m, 3 m, 5 m, 7.5 m, 10 m, 15 m, 20 m. Cables with rugged RJ45 plugs are available in the following lengths: 0.3 m, 0.5 m, 1 m, 2 m, 3 m, 5 m, 10 m, 15 m. For details, refer to the *Industrial Ethernet Connectors Catalog* (Cat. No. G019).
- **\*3.** Cable colors are available in yellow, green, and blue.
- **\*4.** For details, contact your OMRON representative.

#### Cables/Connectors

lt	em	Recommended manufacturer	Model
	Cable	Hitachi Metals, Ltd.	NETSTAR-C5E SAB0.5×4P CP *1
Wire gauge and number of pairs: AWG24, 4-pair cable	Cable	Kuramo Electric Co.	KETH-SB <b>*</b> 1
7 52 ., . pa 5ab.6	RJ45 Connector	Panduit Corporation	MPS588-C <b>*</b> 1
	O-bl-	Kuramo Electric Co.	KETH-PSB-OMR *2
	Cable	JMACS Japan Co., Ltd.	PNET/B *2
Wire gauge and number of pairs: AWG22, 2-pair cable	RJ45 Assembly Connector	OMRON	XS6G-T421-1 <b>*</b> 2

**<sup>\*1.</sup>** We recommend you to use the above Cable and RJ45 Connector together.

**<sup>\*2.</sup>** We recommend you to use the above Cable and RJ45 Assembly Connector together.

#### **Software**

#### **How to Select Required Support Software for Your Controller**

The required Support Software depends on the Controller to connect. Please check the following table when purchasing the Support Software.

Item	Omron PLC System	Omron Machine Automation Controller System		
Controller	CS, CJ, CP, and other series	NJ series		
Inverter	Inverter RX2-series	Inverter RX2-series with EtherCAT Communication Unit 3G3AX-RX2-ECT		
Software	FA Integrated Tool Package CX-One (CX-Drive: Version 3.00 or higher)	Automation Software Sysmac Studio (Version 1.47 or higher)		

## **FA Integrated Tool Package CX-One**

	Specifications			
Product name		Number of licenses	Media	Model
FA Integrated Tool Package CX-One Ver.4.□	The CX-One is a comprehensive software package that integrates Support Software for OMRON PLCs and components.  CX-One runs on the following OS.  Windows 7 (32-bit/64-bit version) / Windows 8 (32-bit/64-bit version) / Windows 8.1 (32-bit/64-bit version) / Windows 10 (32-bit/64-bit version)  CX-One Version 4. includes CX-Drive Ver.3  For details, refer to your local OMRON website.	1 license *1	DVD *2	CXONE-AL01D-V4

<sup>\*1.</sup> Multi licenses are available for the CX-One (3, 10, 30, or 50 licenses).

Note: The RX2-series is supported by CX-Drive version 3.00 or higher.

#### **Automation Software Sysmac Studio**

Please purchase a DVD and required number of licenses the first time you purchase the Sysmac Studio. DVDs and licenses are available individually. Each model of licenses does not include any DVD.

	Specifications	_		
Product name		Number of licenses	Media	Model
	The Sysmac Studio is the software that provides an integrated environment for setting, programming, debugging and maintenance of machine automation controllers including NJ/NX-series CPU Units, NY-series Industrial PC, EtherCAT Slaves, and HMI.	(Media only)	Sysmac Studio (32 bit) DVD	SYSMAC-SE200D
Sysmac Studio Standard Edition Ver.1.□□	Sysmac Studio runs on the following OS. ≵1 Windows 7 (32-bit/64-bit version)/Windows 8.1 (32-bit/64-bit version)/ Windows 10 (32-bit/64-bit version)/Windows 11 (64-bit version)	(Media only)	Sysmac Studio (64 bit) DVD	SYSMAC-SE200D-64
	The Sysmac Studio Standard Edition DVD includes Support Software to set up EtherNet/IP Units, DeviceNet slaves, Serial Communications Units, and Support Software for creating screens on HMIs (CX-Designer). For details, refer to your local OMRON website.	1 license *2		SYSMAC-SE201L

<sup>\*1.</sup> Model "SYSMAC-SE200D-64" runs on Windows 10 (64 bit) or higher.

\*2. Multi licenses are available for the Sysmac Studio (3, 10, 30, or 50 licenses).

Note: The RX-series with EtherCAT Communication Unit 3G3AX-RX2-ECT version 1.0 or later is supported by Sysmac Studio version 1.47 or higher.

## **Overview of Inverter Selection**

For detail of Inverter selection, refer to the RX2 series User's Manual. (Man.No.I620).

## **Motor Capacity Selection**

Before selecting an invertor, first the motor should be chosen.In selecting the motor, first calculate the load inertia for the applications, and then calculate the required capacity and torque.

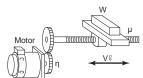
## Make a simple selection (use Formulas for the required output power)

This method of calculation helps select a motor by calculating the output (W) required by the motor to maintain its regular rotations. It does not include calculation of the effect of acceleration/deceleration. Therefore, make allowance for the calculated value to select a motor. This calculation method can be applied to applications that operate constantly such as fans, conveyers, agitators etc.

This calculation method must not be applied to the following applications:

- Those requiring instant start-up.
- Those that frequently repeat operation and stop.
- Those that have a large inertia at the power transfer part.
- · Those that have an inefficient power transfer part.

## For Straight-Line Operation: Normal Power PO (kW)



$$P_0 = \frac{\mu \cdot W \cdot V\ell}{6120 \cdot n}$$

u: Friction Coefficient

W: Mass of Straight-Line travelling part (kg) Vℓ: Speed of Straight-Line Travelling part (m/min) η: Decelerator (Transfer part) Efficiency

## For Rotating Operation: Normal Power PO (kW)



$$P_{o} (kW) = \frac{2\pi \cdot T\ell \cdot N\ell}{60 \cdot \eta} \times 10^{-3}$$

Tℓ: Load Torque (Load Shaft) (N·m) N €: Load Shaft Rotation Speed (r/min)

## **Detailed Selection Method (R.M.S** Algorithm)

This method helps to select a motor by calculating the effective torque and maximum torque required to achieve a certain pattern of operation for the application. It selects a motor that is optimal for a particular operation pattern.

#### Calculate the inertia with a Motor Shaft **Conversion Value**

Calculate inertias of all the components with the formula for inertia calculation shown below to convert them to a motor conversion value.



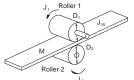
$$J_{W} = J_{1} + J_{2} = \left(\frac{M_{1} \cdot D^{2}}{8} + \frac{M_{2} \cdot D^{2}}{4}\right) \times 10^{-6} (kg \cdot m^{2})$$

- J, : Cylinder Inertia (kg·m²)
- M.: Mass of Cylinder (kg)
- J<sub>2</sub>: Inertia from Object (kg·m<sup>2</sup>)
- Ma: Mass of Object (kg)

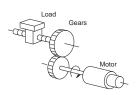
$$J_{w} = J_{1} + J_{2} + J_{3} + J_{4} = \left(\frac{M_{1} \cdot D_{1}^{2}}{8} + \frac{M_{2} \cdot D_{2}^{2}}{8} \cdot \frac{D_{1}^{2}}{D_{2}^{2}} + \frac{M_{3} \cdot D_{1}^{2}}{4} + \frac{M_{4} \cdot D_{1}^{2}}{4}\right) \times 10^{-6} (kg \cdot m^{2})$$



- Jw: Inertia (kg·m²)
- J₁: Cylinder 1 Inertia (kg·m²)
- J<sub>2</sub>: Inertia from Cylinder 2 (kg·m²)
- J<sub>3</sub>: Inertia from Object (kg·m<sup>2</sup>)
- J<sub>4</sub>: Inertia from Belt (kg·m<sup>2</sup>)
- D.: Cylinder 1 Diameter (mm)
- Da: Cylinder 2 Diameter (mm)
- M.: Mass of Cylinder 1 (kg)
- Mass of Cylinder 2 (kg)
- M3: Mass of Object (kg)
- M.: Mass of Belt (kg)



- J<sub>1</sub>: Roller 1 Inertia (kg·m<sup>2</sup>)
- J<sub>2</sub>: Roller 2 Inertia (kg·m<sup>2</sup>)
- D,: Roller 1 Diameter (mm)
- D<sub>2</sub>: Roller 2 Diameter (mm)
- M : Work Equivalent Mass (kg)



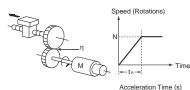
- $J_1 = J_1 + G^2(J_2 + J_W) (kg \cdot m^2)$
- J.: Load Inertia of Motor Shaft Conversion (kg·m2)
- Jw: Load Inertia (kg·m²)
- J.: Gear Inertia on Motor Side (kg·m²)
- J<sub>2</sub>: Gear Inertia on Load Side (kg·m²)
- Z,: Number of Gear Teeth on Motor Side
- Z.: Number of Gear Teeth on Load Side

Gear Ratio G = Z<sub>1</sub>/Z<sub>2</sub>

## Calculate Motor Shaft Conversion Torque and **Effective Torque**

Calculate the acceleration torque from the load torque calculated from both the motor shaft conversion value and the motor rotor inertia. Then Combine this acceleration torque and the Load torque calculated from the friction force and the external force that are applied to the load. Now you get the required torque to operate a motor.

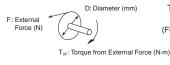
#### **Acceleration Torque**



$$T_A = \frac{2\pi N}{60t_A} \left( J_M + \frac{J_L}{\eta} \right) (N \cdot m)$$

- T<sub>A</sub>: Acceleration/Deceleration Torque (N·m) J<sub>1</sub>: Motor Shaft Conversion Load Inertia (kg·m<sup>2</sup>)
- J<sub>M</sub> : Inertial of Motor Itself (kg⋅m²)
- η : Gear Transmission Efficiency
- N : Motor Rotation Speed (r/min)

#### Motor Shaft Conversion Load Torque (External Force/ Friction)



$$T_W = F \cdot \frac{D}{2} \times 10^{-3} (N \cdot m)$$

(Friction is generally,

μ: Friction Coefficient



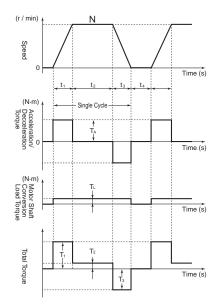
- $T_L = T_W \cdot \frac{G}{\eta} (N \cdot m)$
- T<sub>1</sub>: Motor Shaft Conversion Load Torque (N·m)
- Tw: Load Torque (N-m)
- Z.: Number of Gear Teeth on Motor Side
- Z<sub>2</sub>: Number of Gear Teeth on Load Side
- Gear (Deceleration) Ratio G = Z<sub>1</sub>/Z<sub>2</sub>

#### **Calculation of Total Torque and Effective Torque**

Effective Torque: TRMS (N·m)

$$= \ \sqrt{\frac{\ \Sigma \left(T_{i}\right)^{2} \cdot t_{\ i}}{\Sigma t_{\ i}}} = \ \sqrt{\frac{T_{1}^{2} \cdot t_{1} + T_{2}^{2} \cdot t_{2} + T_{3}^{2} \cdot t_{3} + T_{4}^{2} \cdot t_{4}}{t_{1} + t_{2} + t_{3} + t_{4}}}$$

Maximum Torque:  $T_{MAX} = T_1 = T_A + T_L$ 



Note: Please make use of the Servo Motor selection software, which can calculate the motor shaft conversion inertia and effective/maximum torque, as above.

#### **Motor Selection**

Use the formula below to calculate the motor capacity from the effective torque and the maximum torque that were obtained above. Select the larger of the two generated values as the motor capacity. Select a motor the capacity of which is larger than the calculated value and makes allowance for an error.

#### **Motor Capacity corresponding to Effective Torque**

Motor Capacity (kW) =  $1.048 \cdot N \cdot T_{RMS} \cdot 10^{-4}$ 

N: Maximum Rotations (r/min)

## **Motor Capacity capable of Providing Maximum Torque**

Motor Capacity (kW) =  $1.048 \cdot N \cdot T_{MAX} \cdot 10^{-4} / 1.5$ 

N: Maximum Rotations (r/min)

#### **Inverter Capacity Selection**

Select an inverter that can be used for the selected motor in the process of "Motor Selection".

Generally, select an inverter which fits the maximum applicable motor capacity of the selected motor.

After selecting an inverter, check if it meets with all of the following conditions. If it does not, select an inverter that has a one class larger capacity and check the feasibility again.

# Motor Rated Current $\leq$ Inverter Rated Output Current Maximum Time of Continuous Torque Output Time in an Application $\leq$ 1 minute

Note: 1. Where the inverter overload capacity is "120% of Rated Output Current for 1 minute", check it for 0.8 minute.

2. Where a 0 Hz sensor-less vector control is being used, or where torque must be maintained for 0 (r/min) rotation speed and where 150% of the rated torque is frequently required, use an invertor which is one rank larger than the one selected by the above method.

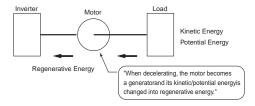
## Outline of Braking Resistor Selection Importance of Braking Resistor

If the regenerative energy generated in deceleration or descent in an application is too great, the main circuit of an inverter may have an increased voltage and it may be damaged.

Because the inverter usually contains the overvoltage LAD stop function, it is not actually damaged. However, the motor stops detecting an error, making a stable and continuous operation disabled. Therefore, you must discharge the regenerative energy outside of the inverter.

#### What is Regenerative Energy?

A load connected to a motor has kinetic energy when rotating, and potential energy when it is located in a high position. When the motor decelerates, or when the load descends, the energy is returned to an inverter. It is known as regeneration, and the energy generated by the phenomenon is known as regenerative energy.



#### **Preventing Breaking Resistence**

The following are methods to prevent the connection of braking resistance.

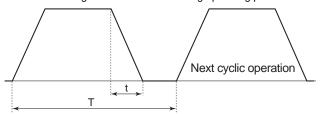
These methods will make the deceleration time increase, so check if it will not cause problems.

- Enable the deceleration stall prevention (enabled in factory settings) (It will automatically increase deceleration time not to cause an overvoltage to stop the motor).
- Set a longer deceleration time. (Cause the regenerative energy to decrease per unit of time.)
- Disable Free-Run. (Prevent the regenerative energy from returning to an inverter.)

#### Make a Simple Selection for Braking Resistors

It can be a simple selecting method by using the ratio of time in which regenerative energy is produced in a normal operating pattern.

Calculate the usage ratio from the following operating pattern.



Usage Rate =  $t/T \times 100$  (% ED)

- t : Deceleration Time (Regenerative Time)
- T : Single Cycle Operation Time

%ED is the unit used for a usage rate.

The usage rate is used as the ratio of deceleration time (regenerative operation time) to simplify the selection of the braking options.

# For Models with a Built-in Braking Circuit (3G3RX2 200 V with a capacity of 22 kW or lower, 3G3RX2 400 V with a capacity of 37 kW or lower)

Select the braking resistor based on the usage rate calculated from the operation patterns.

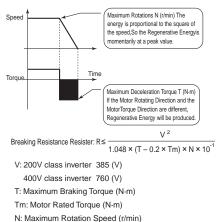
Refer to the braking resistor list described in the User's manual and catalog, and connect it according to your Inverter.

# For Models without a Built-in Braking Circuit (3G3RX2 200 V with a capacity of 30 kW or higher, 3G3RX2 400 V with a capacity of 45 kW or higher)

Select the regenerative braking unit and the braking resistor. Refer to the regenerative braking unit and braking resistor lists described in the User's manual and catalog, and connect them according to your Inverter.

When the usage ratio for the braking resistor selected on the previous page exceeds 10% ED, or when an extremely large braking torque is required, use the method below to calculate a regenerative energy and make your selection.

#### Calculation of Required Braking Resistor

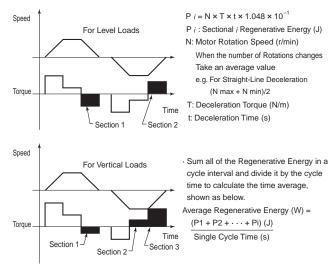


**Note:** Calculate a braking torque using the above "Motor Capacity Selection".

#### Calculation of Average Regenerative Energy

Regenerative Energy is produced when the motor rotation direction and the torque direction are opposite.

Use the following formula to calculate a regenerative energy per cycle interval.



Note: 1. Forward rotation direction is forward for the speed, and the torque in the forward rotation direction is forward for the torque.

Calculate a braking torque using the above "Motor Capacity Selection".

#### **Braking Resistor Selection**

Select a Braking Resistor from the required braking resistance and average regenerative energy on the left.

- Required Braking Resistence ≥ Resistence of Braking Resistor ≥ Minimum Connection Resistence of Invertor or Regenerative Braking Unit
- Average Regenerative Energy ≤ Permissible Power for Braking Resister

Note: 1. If a resistance that has a less then the minimum connectable value is connected on an inverter or regenerative braking resistor unit, the internal breaking transistor can be damaged. When the required braking resistance is less than the minimum connectable resistance, change the inverter or regenerative energy braking to the one having a larger capacity and a minimum connection resistance less than the required braking resistance.

- Two or more regenerative braking units can be operated in parallel. Refer to the following formula to know the braking resistance value in such a case.
   Braking Resistence (Ω) = (Required Braking Resistance as calculated above) × (No. of Units in use)
- 3. Do not use the above formula to select a generative braking resistance value. 150 W does not reflect a permissible power capacity, but the maximum rated power per unit of resistance. The actual permissible power varies according to a resistance.

# **High-function General-purpose Inverters RX2 Series Related Manuals**

Man. No.	Model	Manual
1620	3G3RX2-□□□□	3G3RX2 Series High-function General-purpose Inverter User's Manual
1663	3G3AX-RX2-ECT	3G3RX2 Series EtherCAT® Communication Unit User's Manual
1622	3G3RX2-□□□□□ CXONE-AL□□D-V□	Inverter RX2 Series DriveProgramming User's Manual
W463	CXONE-AL□□D-V□	CX-One FA Integrated Tool Package SETUP MANUAL
W453	CXONE-AL□□D-V□ WS02-DRVC01	CX-Drive OPERATION MANUAL

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Note: Do not use this document to operate the Unit.

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Cat. No. **I921-E1-06** 0123 (0319)