

Standard

Rated torque: 3.4 to 500N·m

Popular standard type pursuing cost performance.
 Suitable for various applications.
 Compact design. Higher torque density and optimized thermal structure and magnetic circuitry have reduced the volume ratio by 25% from previous models (ND and ND-c Series).

Ideal for converting the AC servo motor + reducer mechanism into a direct drive system

Application examples

Point!

Wafer carrier devices/■Food carrier devices/■Filling machines/■Capping machines/■Roll feeders/
 Laser beam machines/■Laminating machines/■FPD pasting machines/■Die cutters/
 Screen printing machines/■Contact and non-contact inspection machines■Index tables



Feeding and winding drive (roll-to-roll application devices): Laminating machines, coaters, surface inspection machines, etc. Replacing a powder clutch or brake





τDISC



High-speed rotation Rated torque: 8 to 24N·m

OHigh-speed rotation specification model of the ND-s Series.

OPursuing compactness and high-speed operation.

◎ Lineup of motors whose rated rotation speed ranges from 11 to 15 rps (660 to 900 rpm).

Ideal for applications that require high-speed and high-precision operation

Application examples

- Die bonders
- Sorters

1

- Spin coaters
- Spin washers

High-speed positioning examples

90-degree positioning time: **36msec**

180-degree positioning time: 60msec

Accuracy at the arm tip: $\pm 4 \ \mu$ m (completion range: ± 10 pulses)

- Motor used and specifications
 ND140-95-LS-HS Type
 Rated/maximum torque: 15/37N·m
 Rated rotation speed: 11rps
 Rotor moment of inertia: 0.00134kg·m³
 Detection pulse: 1,600,000ppr
- Load specifications
 Arm load (double edge): Weight of 0.086 kg
 (208 mm from center to tip)
 Load inertia moment ratio: Approx. 0.5 times





High rigidity and high precision Rated torque: 10 to 2000N·m

OHigh-rigidity type pursuing high rigidity and high precision. Significant improvement in moment rigidity, axial rigidity, and rotor torsional rigidity.

OPursuing positioning accuracy and run out accuracy.

© Enabling stable operation even at the inertia ratio of 2,000 times.



Ideal for applications that require stable operation for loads with large inertia



Positioning operation waveforms when the inertia ratio is 527 times



DD160-146-LS Type [Motor used and specifications]

- Rated/maximum torque: 27/62.5N·m
- Rotor moment of inertia: 0.0074kg · m
- Load specifications (disk)
 - Load inertia moment: 3.9kg m² (527 times larger than rotor moment of inertia)
- Positioning operation: 90°

auDISC

- Paired servo driver: VPH-HA Type
- * These values may vary depending on the load setting condition and other factors. They are not guaranteed values.

Application examples

Scribers/ FPD pasting machines/ Screen printing machines FPD inspection machines/ Wafer dicing machines/ Packaging machines Wafer processing machines/Wafer inspection machines/X-ray analyzers/ PE printing machines/Precision processing and measurement machines/Die casting machines



Ball screw drive :

Die casting machines, servo presses, etc.

- High-response operation
- The hollow structure makes the device simpler Improvement in environmental friendliness and safety due to not using a hydraulic system



<text><text><list-item><list-item><list-item>

Ideal for applications that require small operation angles and high-speed operation





 Application examples
 Test handlers/ Taping machines/ Appearance inspection machines/ Vibration generators

 Automotive parts testing machines/ Torque testing machines/ Vibration generators



Testing machine drive :

Torque testing machines, material testing machines, durability testing machines, etc.
 High-response operation
 Space savings and improved quietness
 Improvement in environmental friendliness and safety

Torque meter

DISC Customization

In addition to the standard TDISC lineup, we can offer custom-made features, such as those shown below, to meet your needs for special specifications.

Custom Made

Custom Made

Improved speed stability

Based on the ND250-s and ND400-s Types of the ND-s Series, speed stability is improved by reducing motor torque ripples, mounting a high-precision encoder, etc.

Speed variation [At speed of 2 rpm]

small range of angles



Custom Made

Anti-fretting measures

Fretting is a phenomenon that occurs when the rolling elements (e.g., rollers) of a bearing reciprocate repeatedly as if to vibrate, against the metal surfaces of the inner and outer rings at the same location within a very small range of angles. In this case, as new oil films do not form, and parts that are in contact with the metal surfaces wear out.

We have taken measures to reduce bearing fretting and extend the life of the bearing when the rolling elements reciprocate repeatedly within a very small range of angles and cannot turn periodically.

τ DISC anti-fretting specifications

We optimize the bearing preload and select the suitable bearing grease through actual product evaluation, appropriate for your operating conditions.





* For information about the availability of customization, contact our sales staff.



List of paired servo drivers of each τ DISC Series

O:Pairing possible △:Connector and cable changes

	V	PH Series	V	CII Series	VPS Series			
		Sup	ported networks	Sup	ported networks	Supported networks		
		SERWORK	SSCNET III/H	SERVOS	SSCNET ////H			
		CC-Link		(C-Link	CC-Link		
		Eth	ner CAT.					
	MECHATROLINK		N	IECHATROLINK				
τDISC		Pairing	Servo driver output capacity	Pairing	Servo driver output capacity	Pairing	Servo driver output capacity	
	ND110-65-FS(AC100V)	0	100W/200W	0	100W/200W	0	200W	
	ND110-65-FS (AC200V)	0	200W	0	200W	0	400W	
	ND110-85-FS (AC100V)	0	200W	0	200W	0	200W	
	ND110-85-FS (AC200V)	0	400W	0	400W	0	400W	
	ND140-65-FS	0	400W	0	400W	0	400W	
	ND140-70-LS	0	400W	0	400W	0	400W	
	ND140-95-LS	0	800W	0	800W	0	800W	
	ND180-55-FS	0	800W	0	800W	0	800W	
ND-S	ND180-70-LS	0	800W	0	800W	0	800W	
Series	ND180-95-LS	0	800W	0	800W	0	800W	
	ND250-55-FS	0	800W	0	800W	0	800W	
	ND250-70-LS	0	800W	0	800W	0	800W	
	ND250-95-LS	0	1.5kW	0	1.5kW	0	1.6kW	
	ND400-65-FS	0	2.2kW	0	2.2kW	-	-	
	ND400-70-LS	0	2.2kW	0	2.2kW	-	-	
	ND400-95-LS	0	3.3kW	0	4kW	-	-	
	ND400-160-LS	0	7kW	0	7.5kW	-	-	
	ND110-85-FS-HS	0	400W/800W	0	400W/800W	0	400W/800W	
ND-s HS	ND140-70-LS-HS	0	800W	0	800W	0	800W	
Series	ND140-95-LS-HS	0	1.5kW	0	1.5kW	0	1.6kW	
	ND180-95-LS-HS	0	1.5kW	0	1.5kW	0	1.6kW	
	DD160-96-LS	0	400W	0	400W	0	400W	
	DD160-105-FS	0	400W	0	400W	0	400W	
	DD160-146-LS	0	800W	0	800W	0	800W	
	DD250-90-LS	0	800W	0	800W	0	800W	
	DD250-138-LS	0	1.5kW	0	1.5kW	0	1.6kW	
	DD250-163-LS	0	1.5kW	0	1.5kW	0	1.6kW	
DD-S	DD400-150-LS	0	3.3kW	0	4kW	-	-	
Series	DD400-200-LS	0	7kW	0	7.5kW/11kW	-	-	
	DD400-250-LS 1.5rps	0	7kW	0	15kW	-	-	
	DD400-250-LS 1rps	0	7kW	0	7.5kW	-	-	
	DD400-250-LS 2rps	-	-	0	15kW	-	-	
	DD630-175-LS		7kW	0	11kW	-	-	
	DD630-225-LS	-	-	0	15kW	-	-	
HD-s	HD140-160-LS	0	800W	0	800W	-	-	
Series	HD140-185-LS	0	1.5kW	0	1.5kW	-	-	
Series	HD180-200-LS	0	2.2kW	0	2.2kW	-	-	

★For detailed specifications, dimensions, etc., of the VPS Series, visit the CKD Nikki Denso website.

VPH Series

Developed exclusively for direct drives. Maximizes the motor performance. Output capacity 100W to 7kW

Lineup

◎ VPH-НА Туре	I/O specification	Speed command operation, torque command operation, and pulse train command operation, and built-in command	operation
© VPH-HB Type	SSCNETⅢ/H specification	Supports SSCNETII/H and SSCNETII. Speed command operation, torque command operation, and position control operation	
© VPH-HC Type	CC-Link specification	Supports CC-Link (Version 1.10) communication. Speed command operation, torque command operation, pulse train command operation, and built-in command ope	ration CC-Link
◎ VPH-HD Type	EtherCAT specification	Supports EtherCAT communication (CiA402 drive profile). Speed command operation, torque command operation, and position control operation	Ether CAT.
◎ VPH-HE Type	MECHATROLINK-III specification	Supports MECHATROLINK-III communication. Speed command operation, torque command operation, and position control operation	MECHATROLINK

* For information about support of the SEMI-F47 standard, contact our sales staff.

Quieter, faster, and easier...



Even greater speed stability

Improved stability during stop

Significant reduction in torque ripples

Reducing torque ripples further improves speed stability. (Reduced by 20% from the conventional model.)

Filtering function during stop

Improved torque accuracy during stop Vibration of a load with large inertia during stop is reduced.

Enhanced low-speed gain switching function

Not only speed but also other items, such as deviation and the presence or absence of command, can be set as the conditions for switching between normal and low-speed gains.

Easy tuning even for a load with large inertia

Automatic feedback filter setting function

Since the feedback filter appropriate for the load is automatically set during auto tuning, the speed detection ripples are reduced, allowing easy tuning even for large inertia loads. Smooth operation can be achieved easily.

Monitoring of multi-axis motion with the master controller

Operation monitoring of speed, torque, deviation, etc., can be done with the master controller when connected to the SSCNETII/H, EtherCAT, or MECHATROLINK-III motion network.

<section-header><section-header>StateStat

◎VСІІ-С1 Туре	Controller specification	Operations such as positioning, spinner, speed control, and torque control can be performed automatically using programs.						
◎ ѴСӏӏ-С6 Туре	Free-curve control specification	Curve operations can be done simultaneously or independently in a flexible manner. Sine wave operation is achieved easily.						
◎ ѴСӏӏ-D7 Туре	SSCNETI/H specification	Supports SSCNETII/H and SSCNETII. Speed command operation, torque command operation, and position control operation						

-Link

Link

★Adding the optional interface enables the driver to connect to MECHATROLINK-III and CC-Link as well.

Cost-focused servo driver Output capacity 200W to 1.6kW *For detailed specifications, dimensions, etc., of the VPS Series, visit the CKD Nikki Denso website.

○I/O specification

In addition to pulse train control and speed control, this driver features a 31-point positioning control function.

© CC-Link specification Pulse train control and CC-Link communication are supported.

System support tool

The enhanced adjustment, monitoring, operation, analysis, and editing functions assist in mechanical system matching and enable efficient start-up.

Data Editing Software

* Some functions and screens of the system support tool for the VCII Series are different

Analysis functions

Oscilloscope function

- The servo data of four channels can be displayed in real time.
- The motor load ratio during repeated operations can be displayed easily.
- The normal trigger function makes it easy to identify changes before and after adjustment.

Frequency response measurement function

 By measuring the frequency response of the mechanical system through automatic motor excitation, the mechanical resonance filter can be set easily.

Frequency spectrum measurement function

 By finding the mechanical resonance point through the measurement of the frequency spectrum during the operation, the mechanical resonance filter can be set easily.

Status display

Status display function

- Various operation information, such as the actual motor operation speed, actual torque command, and current position, is displayed in real time.
- The alarm history, device information, and so on are displayed.

Input/output signal status display function

The input and output signals can be checked easily during the start-up operation.

Device monitoring function

The memory area inside the driver can be displayed and edited in real time.

Status display screen

👩 Stat	e indicatio	n						- 0	×
State	Alarm	Driver in	nfo Enc	oder info					
All it	ems Ve tor	locity & que	Other	Abnorr	nality	User custom			
No.	Item				Data	Unit			
C001	Actual ope	eration spe	ed of mot	or	-1799.557	deg/se	ec		
C002	Operable i	max speed			1800.000	deg/se	ec 🛛		
C003	Analog sp	eed comm	and value		0.131	deg/se	ec .		=
C004	Actual mo	tor operat	ing rotatio	nal speed	-299	rpm			
C005	Actual tor	que comm	iand value		-8.8	%			
C006	Peak torq	ue comma	nd value		42.0	%			
C007	Analog To	rque comr	nand value		0.0	*			
C008	Load facto	or of moto	r		8.8	*			
C009	+ Torque	limit value		250.0	%			*	
٠.) E
								Clear	Close

Adjustment functions

Auto tuning function

- A separate screen is displayed for auto tuning, making it easy to change the parameters necessary to execute the tuning.
- The automatic feedback setting function automatically sets the feedback filter appropriate for the load inertia ratio, thus enabling smooth operation.
- The expected operation of the auto tuned motor and the result are displayed.

Real-time servo adjustment function

• The function that adjusts the gain level after auto tuning makes the adjustment even easier.

🔄 Auto-tunina

Operating parameters received Operating parameters setting

I set the ratio of the spe

Inertia magnification selection Please change if the ine

FB filter setting method Automatic

FB filter order selection Secondary

Start(S)

I choose how to set up a feedback filte

Gain 0

Both

ed of operation

150 or less times

tia is large, resulting in a ERROP

END

Tuning gain selection

Operation direction selection

Operating ratio

Maximum torque

Filter settings

FB filter frequency

Status

The speed and position loop gain can be adjusted in real time.

Test operation function

• A test operation can be executed with the positioning function.

Self-diagnosis function

- Self-diagnosis of the servo driver can be done.
- Data editing

Parameter editing function

• The parameters such as gain, filter, command, and signal are grouped to make the editing work easier.

Program editing function

• Programs can be created and edited using the operation commands in internal command mode.

Indirect data editing function

This function creates and edits the indirect data to be used for program operation.

_							
🜀 Switch BO	х						• X
Output sign	nal condition	display					
PN2	PN1	PE2	PE1	SZ	RDY	WNG	ALM
BRK	VCP	PRF	ZRDY	ZZ	ZN	PZ2	PZ1
		MTON	OTO	HLDZ	HCP	EMGO	LIM
- General pu	rpose outpu	t signal co	ndition display	,			
OUT8	OUT7	OUT6	OUT5	OUT4	OUT3	OUT2	OUT1
- Input signa							
FOT	TL	CLR	DR	SON	EMG	ARST	RST
			CMDZ	RVS	GSL2	GSL1	ROT
Speed Mode	Torque	Mode	Pulse Mode	NC Mode			
SS1-8 SEL No:0 Command	Address:0				Input signal TRG ZM <i>RJ</i> (IK ZLS DG FJOG	ZST ZCAN
							Close

Supported OS

- Windows10 32bit/64bit
- Windows8/8.1 32bit/64bit
- Windows7 32bit/64bit

Parameter editing screen

Parameter edit/VPH-801+ND180-70-LS(INC) with load.c0pa0														
Parameter Settings 📄 New 📄 Open 📓 Save 📓 Save As 🖉 Print 🎯 Unit/Gear setting														
Driver/ Gain Filter C Motor setting setting s				Command Signal setting		Communica tion setting		Special spec	Special View all		P225	Gain No. (position loop gain	0	
		L	J		Gain nun	l nber0 ▼]				Max value Mini value Activating timing	0.0 Real-time	
No.	Item				Setting va	alue	Initi	ial value	Unit			[Explana	[Explanation]	
P221	Gain No time cor	. 0 low speed lo nstant	op derivative		0		0		us		*	Set the positio	osition loop	
P222	P222 Gain No. 0 bw speed bop proportional				0.0 0.0 5		*	%		gain. The larger the				
P223	Gain No. 0 low speed loop derivative		0.0		0.0		*	%		setting, the faster th response, but vibration is more				
P224	24 Gain No. 0 speed loop integral torque		0 0		0		ж	%						
P225	Gain No	. O position loop	gain		400.0		20.0		s^-1			If "0" is set, th	e	
P226	Gain No gain	. 0 low speed po	osition loop		200.0		20.0		s^-1		Ξ	following appli	ies.	
P227	P227 Gain No. 0 position loop derivative time constant				0 0		0		us	us		is not performe	formed, but	
P227	P227 Gain No. 0 low speed position loop derivative time constant			0		0) us		operation is performed with the	the -				
P228	228 Gain No. 0 positioning command delay time			0.0		0.0		ms	speed		speed command [P229 Speed fe	i of ed		
4	1			1			1		l	۱.	1	forward].		-
Com	Comparison Transmission to the driver Reception from the driver Close													

-

-

0.30

Motor behavior expected

Remote operation

Switch box function

with the master controller disconnected.

Remote operation can be done easily from a PC

Switch box screen